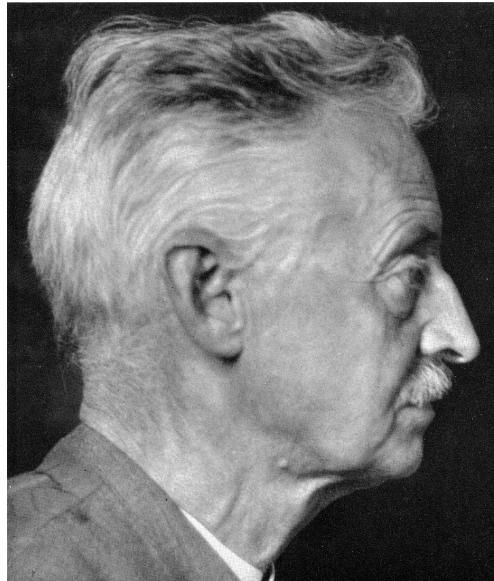


Upon this ROCK I will build my ...

**Upon this ROCK I will build my ...
Stiff Integrators**

Upon this ROCK I will build my ... Stiff Integrators

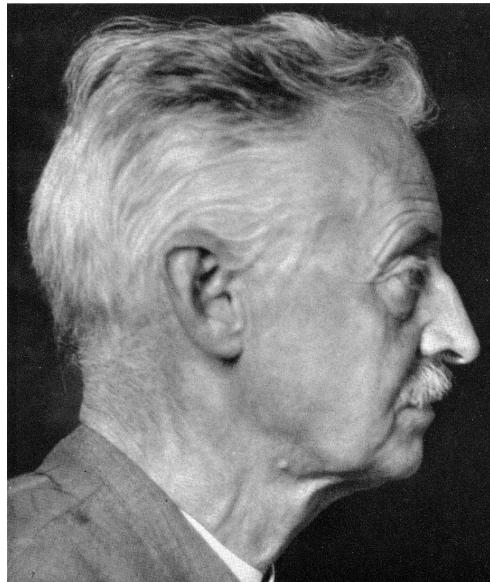
standing on the shoulders of great people ...



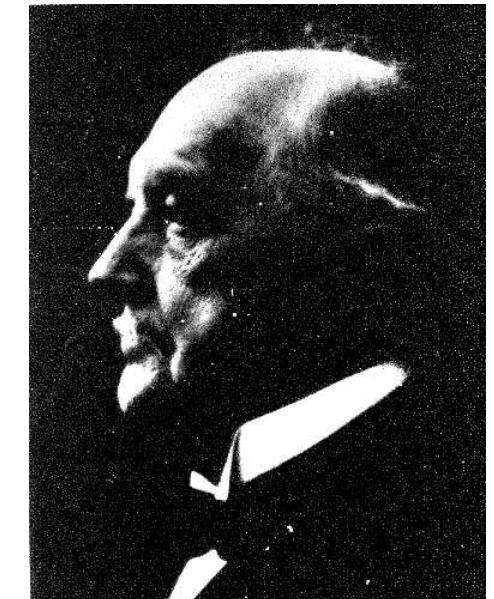
Runge

Upon this ROCK I will build my ... Stiff Integrators

standing on the shoulders of great people ...



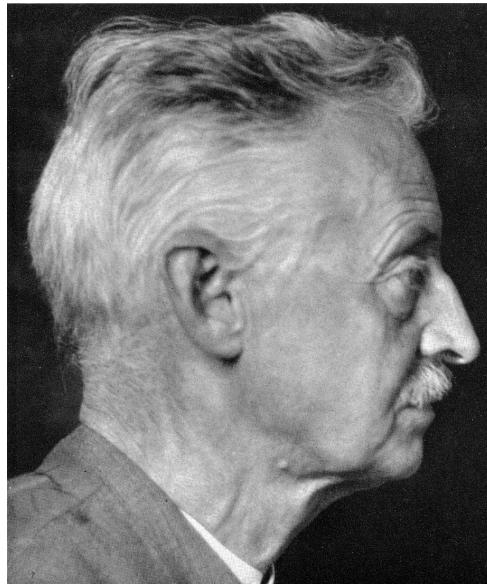
Runge



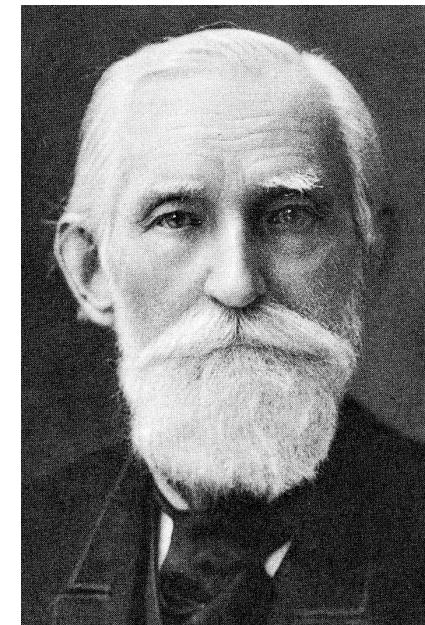
Kutta

Upon this ROCK I will build my ... Stiff Integrators

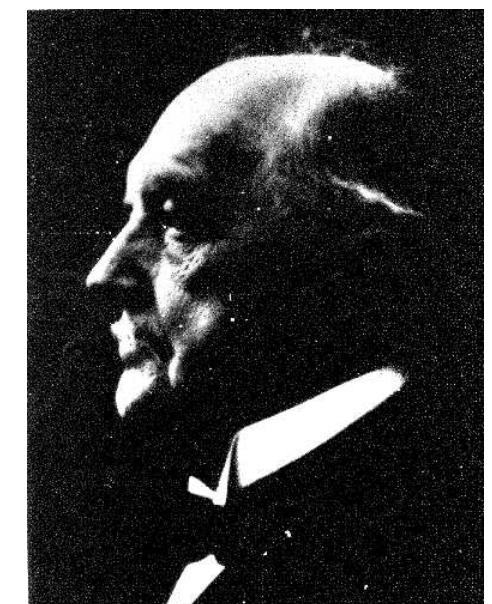
standing on the shoulders of great people ...



Runge



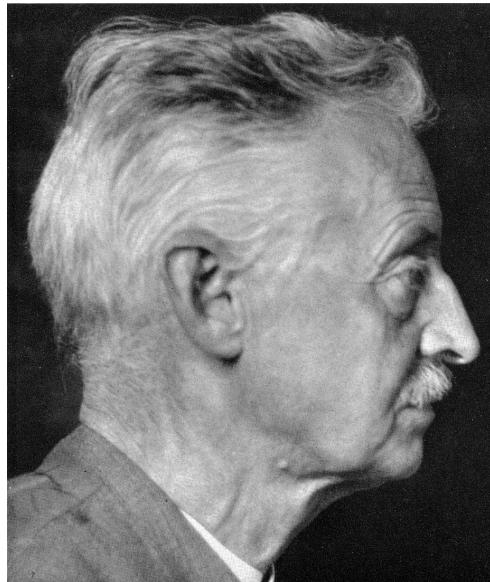
Chebyshev



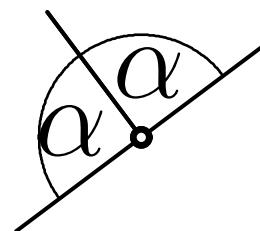
Kutta

Upon this ROCK I will build my ... Stiff Integrators

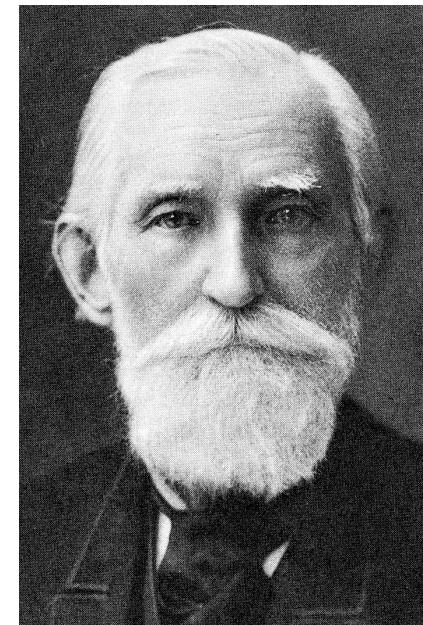
standing on the shoulders of great people ...



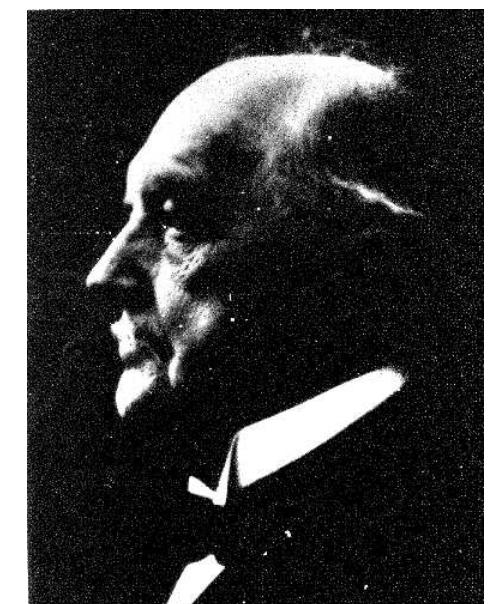
Runge



Orthog.



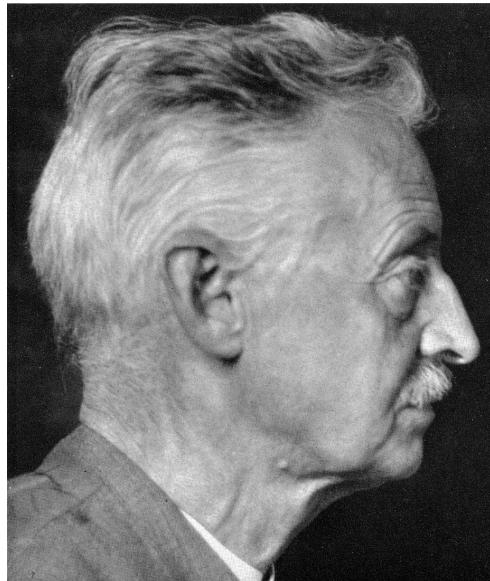
Chebyshev



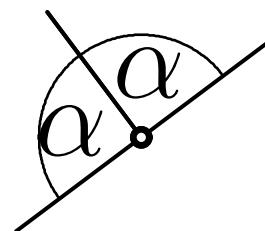
Kutta

Upon this ROCK I will build my ... Stiff Integrators

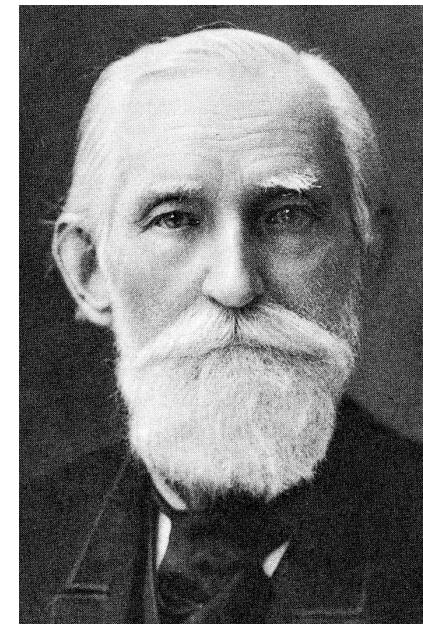
standing on the shoulders of great people ...



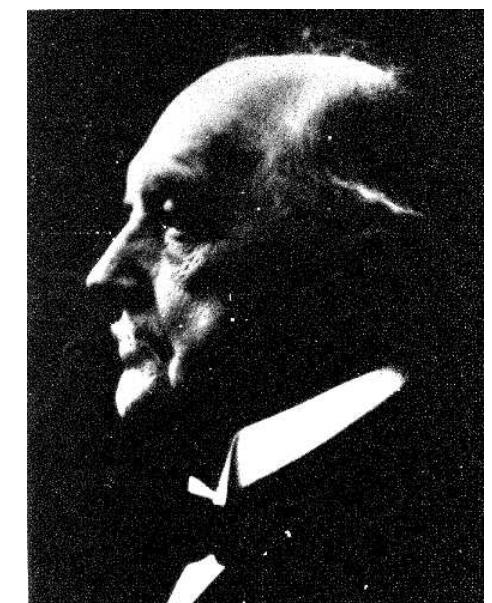
Runge



Orthog.



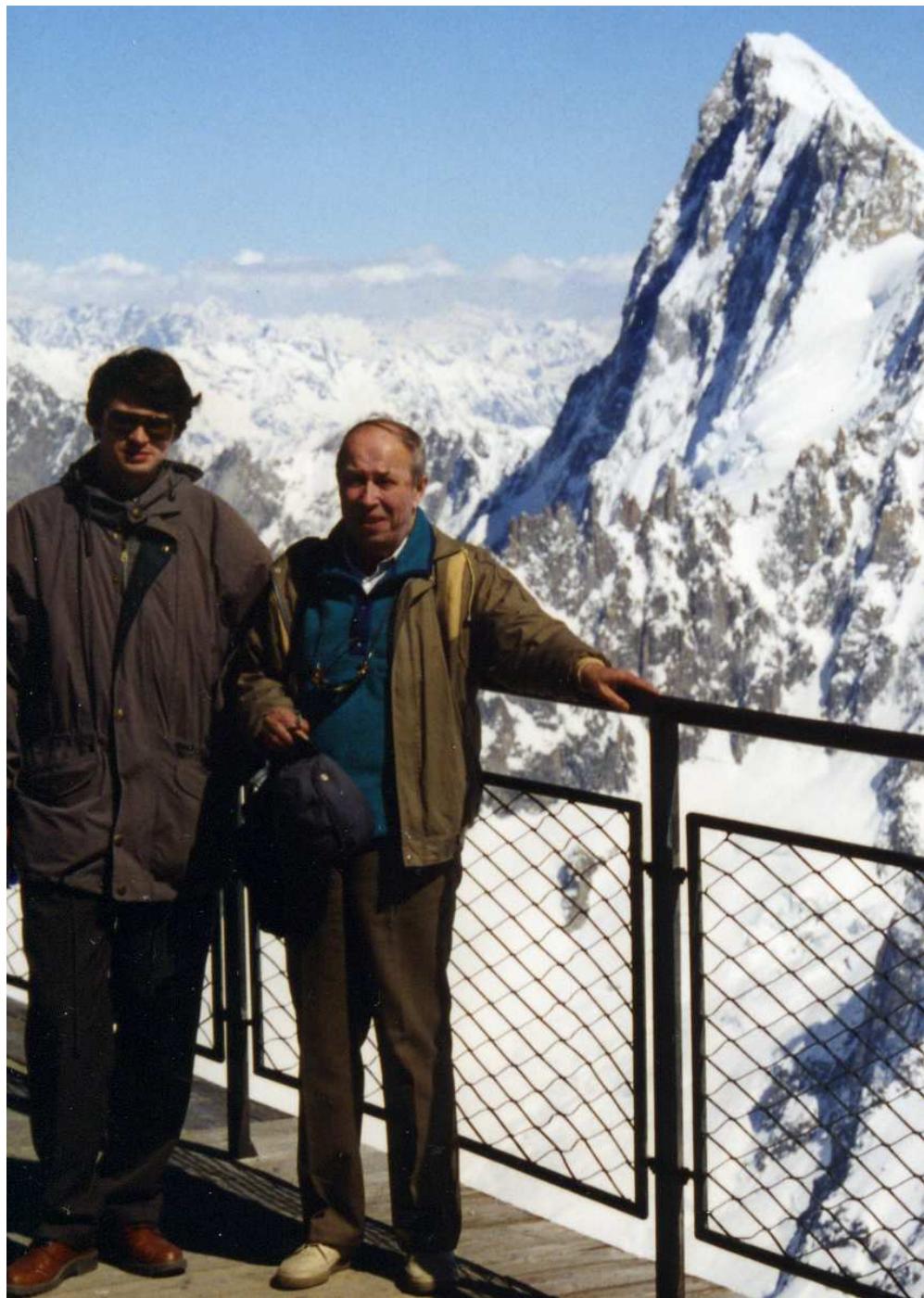
Chebyshev



Kutta

Yuan Chzao Din, Saul'ev, Guillou-Lago, Verwer-Sommeijer ...

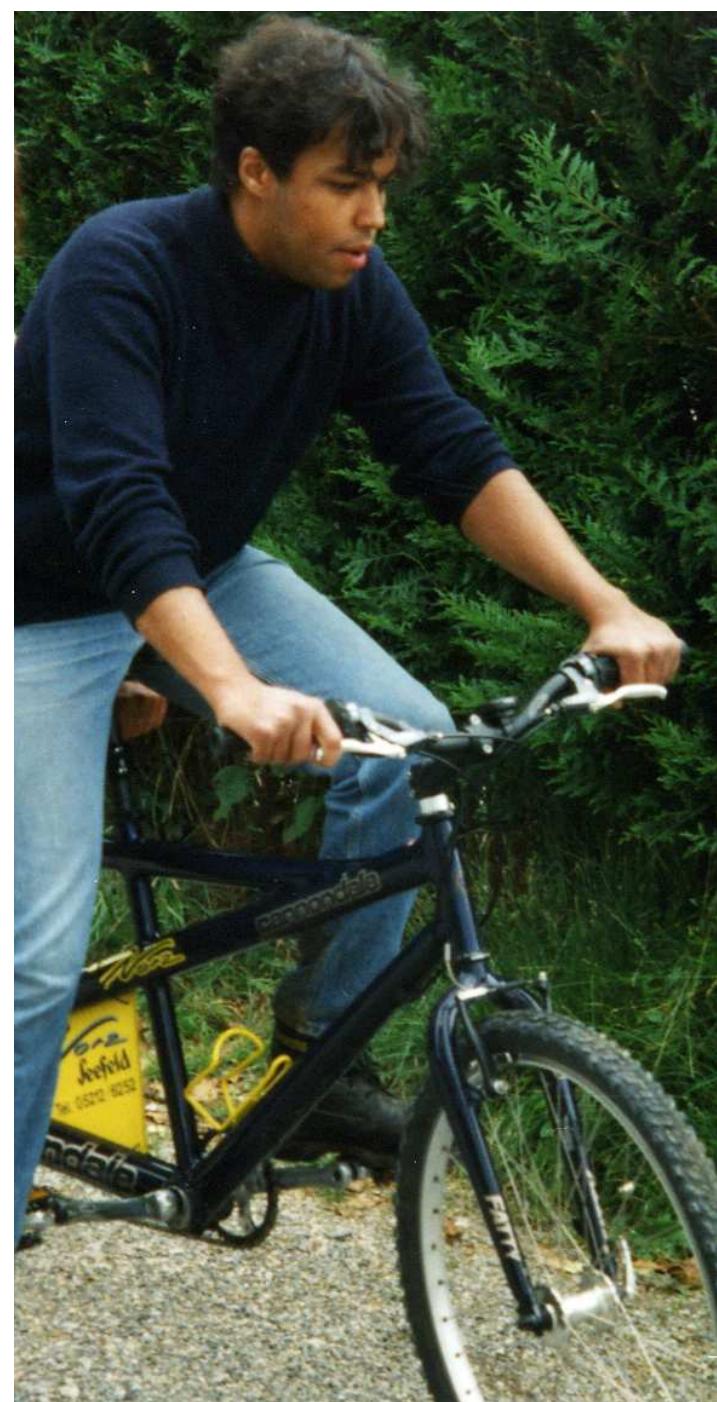
...Lebedev, Medovikov



...Lebedev, Medovikov



... and Assyr Abdulle



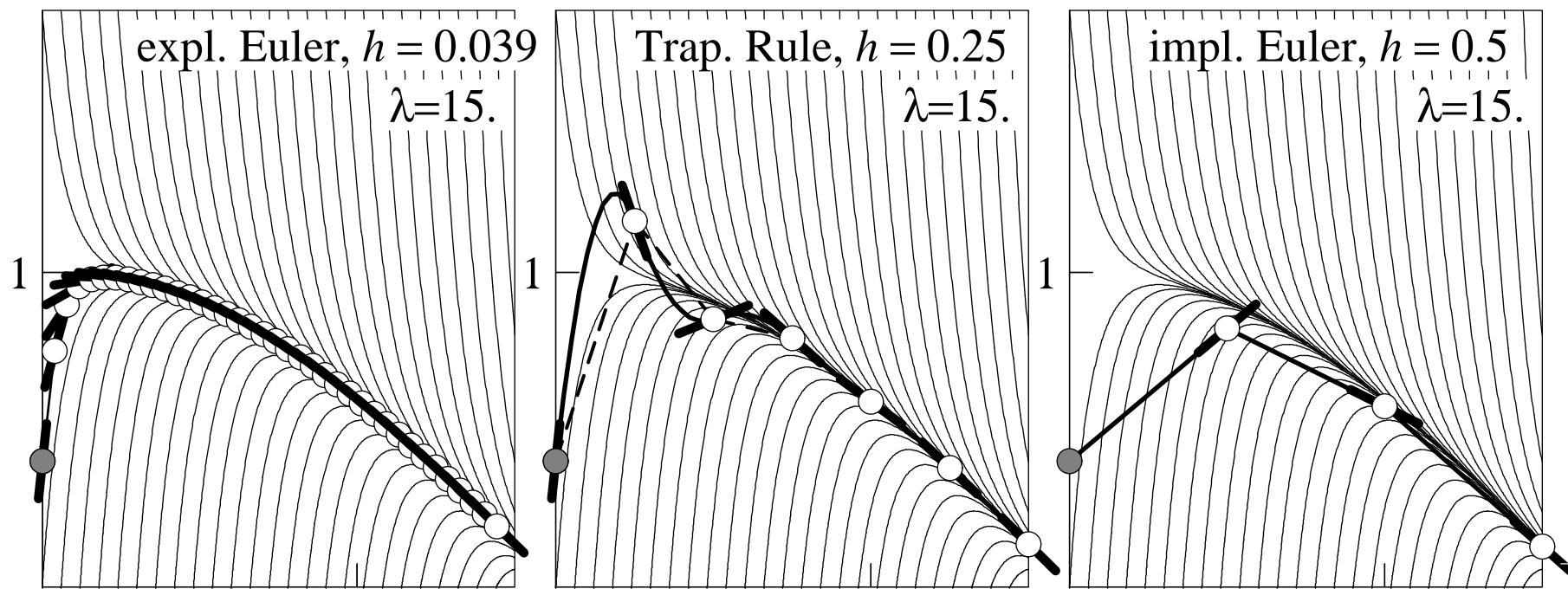
Stiff Equations

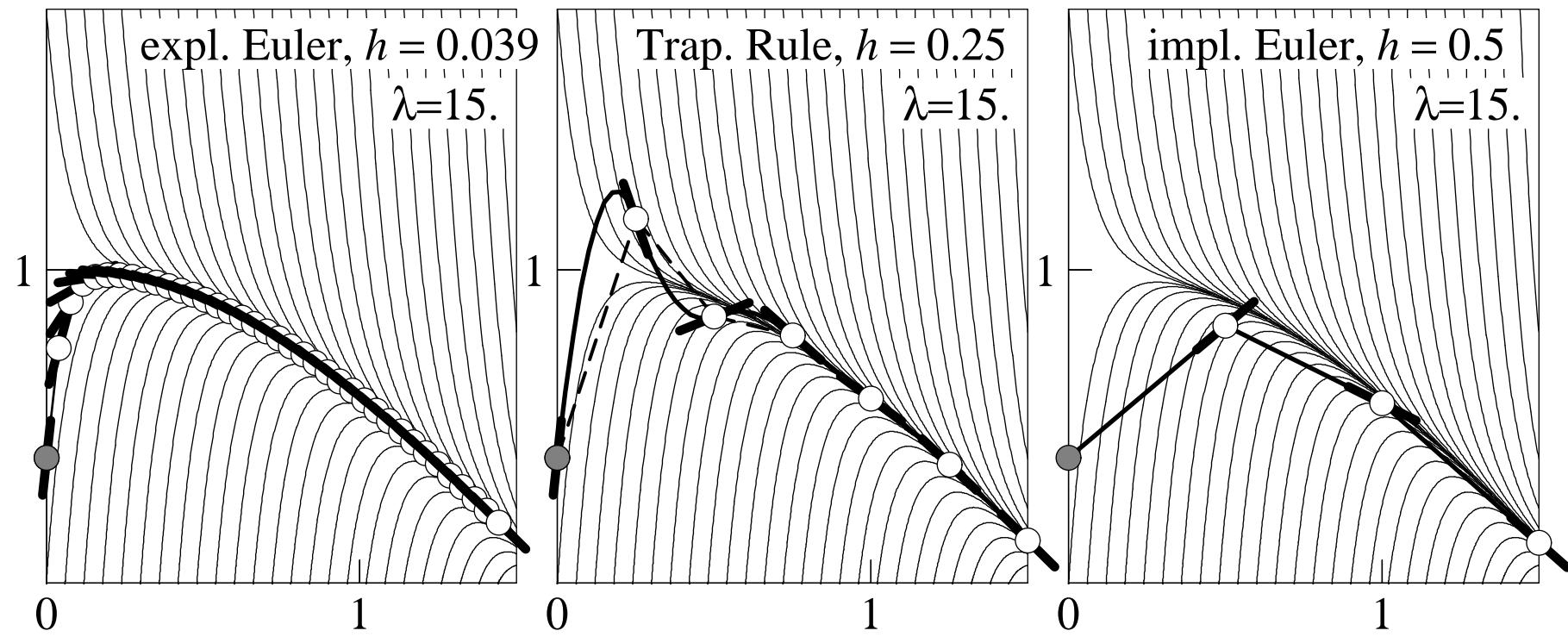
... Around 1960, things became completely different and everyone became aware that the world was full of stiff problems.
(G. Dahlquist in 1985)

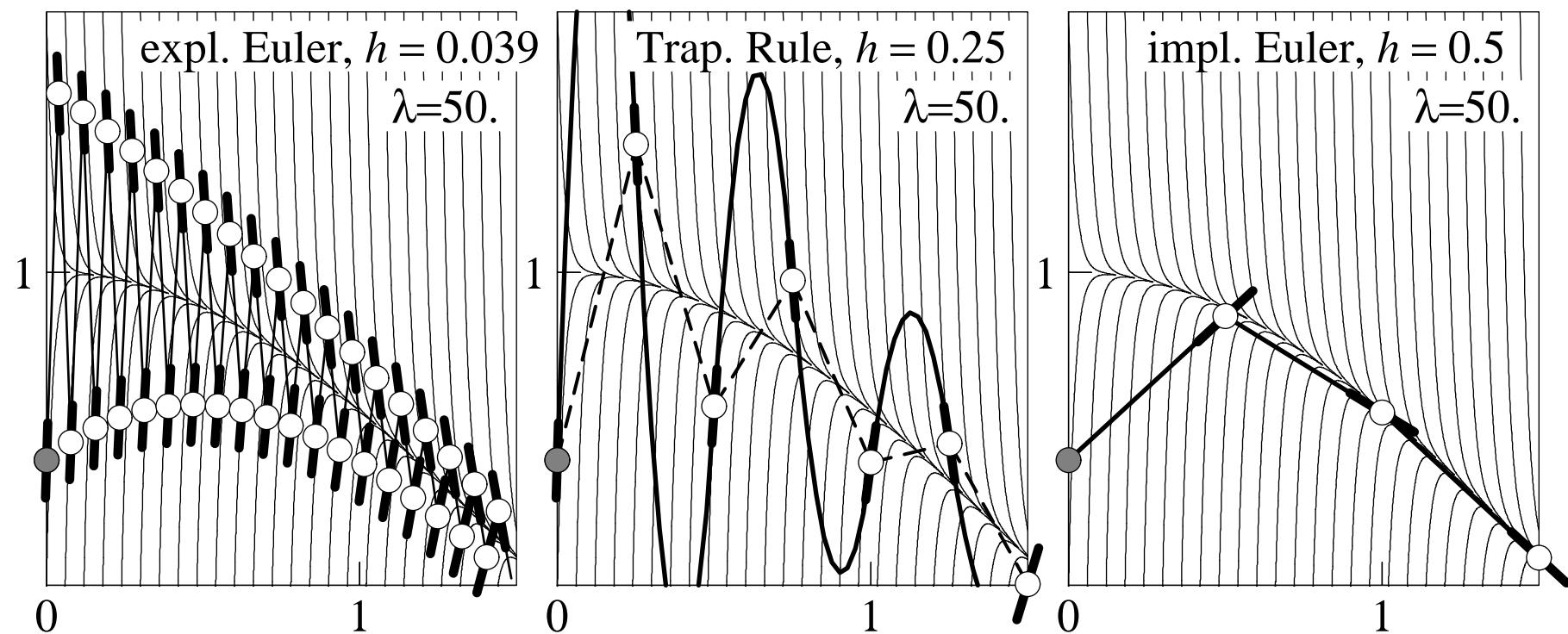
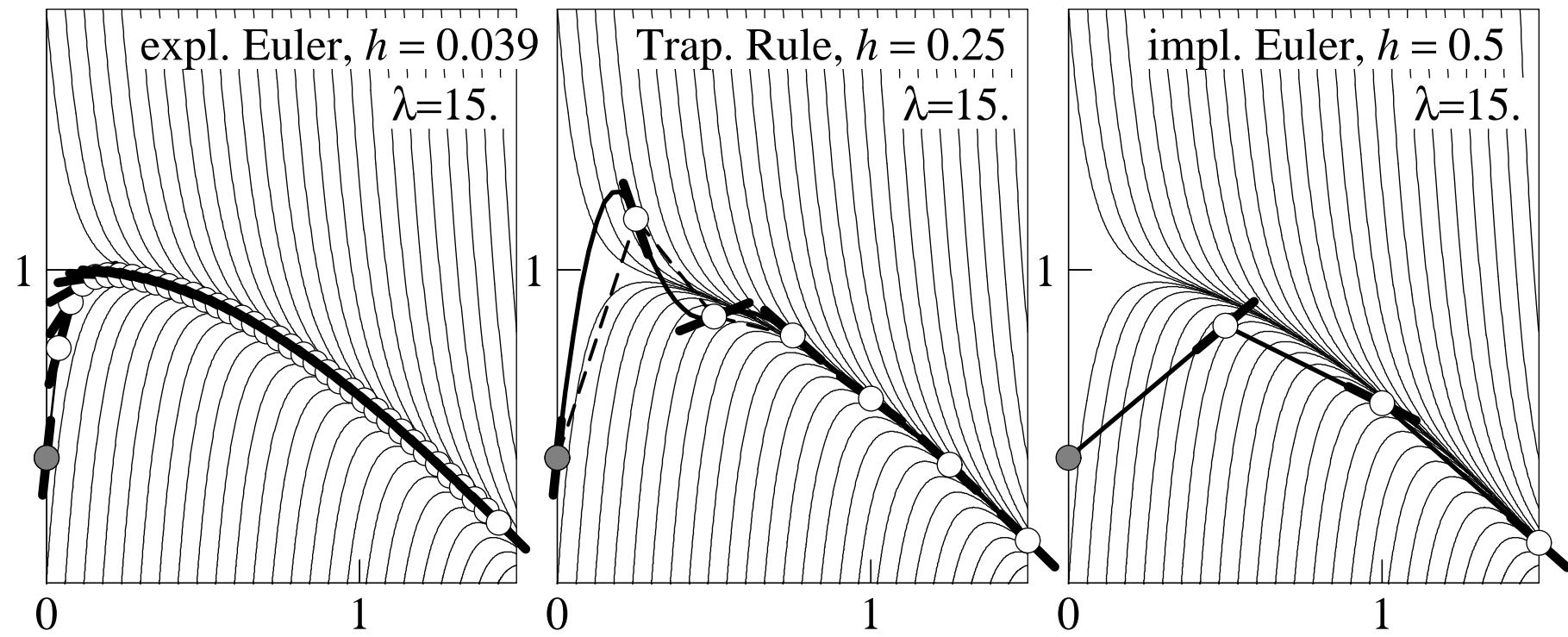
Stiff Problem

= search for a quiet life inside a turbulent world ...

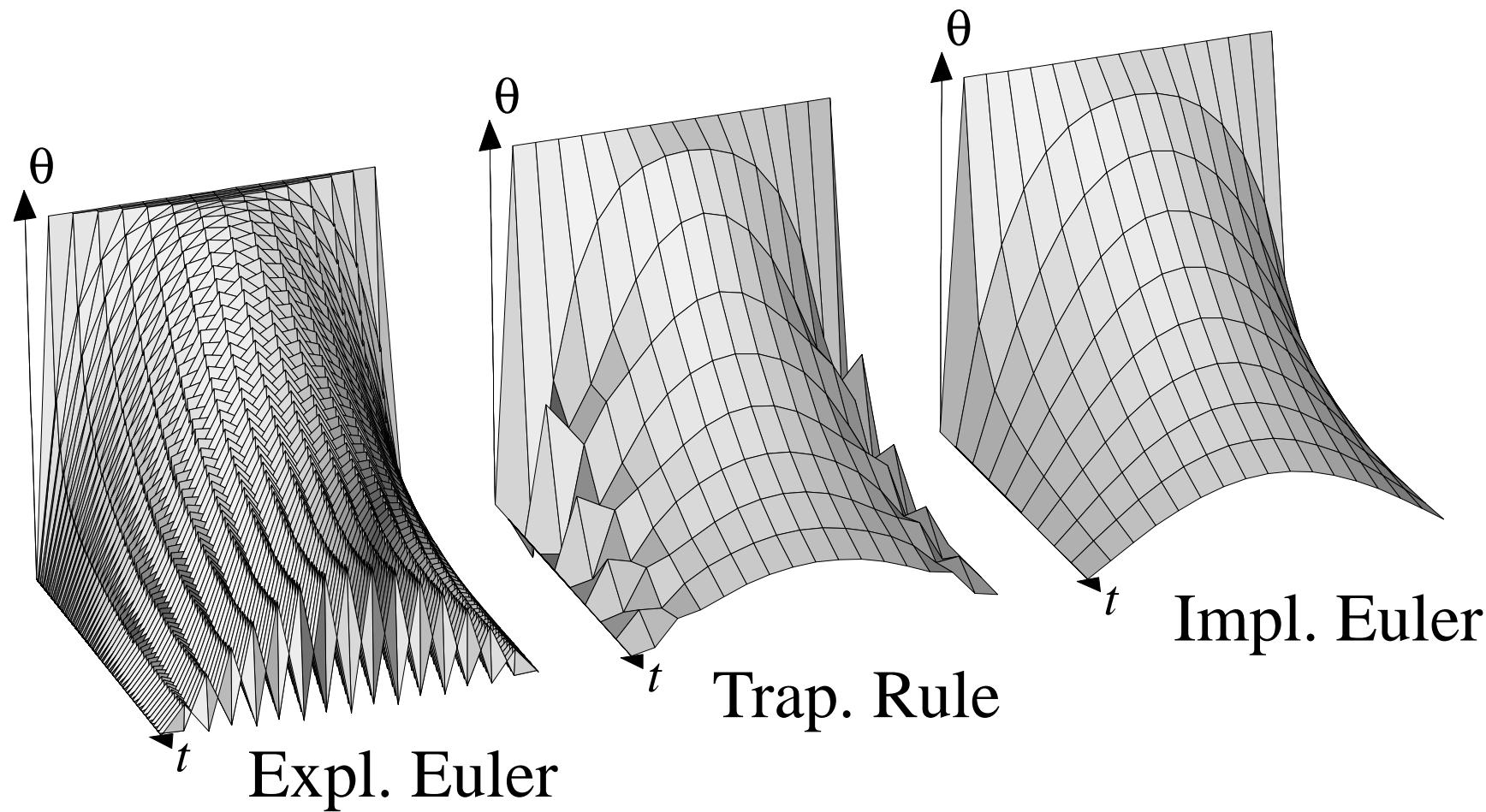
Example: $y' = -\lambda(y - \cos x)$







Another Example. The heat equation $\frac{\partial \theta}{\partial t} = \frac{\partial^2 \theta}{\partial x^2}$



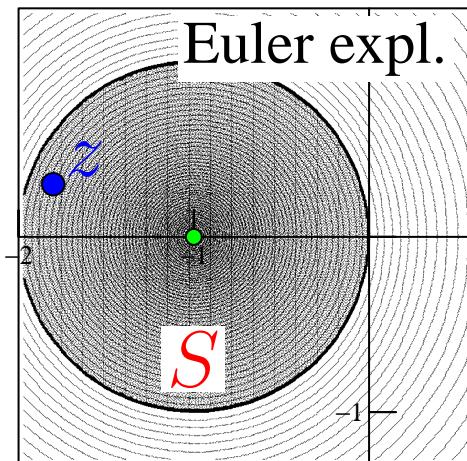
Stability Analysis:

$$y' = \lambda y \quad \Rightarrow \quad y_{n+1} = R(z)y_n \quad z = h\lambda;$$

Examples:

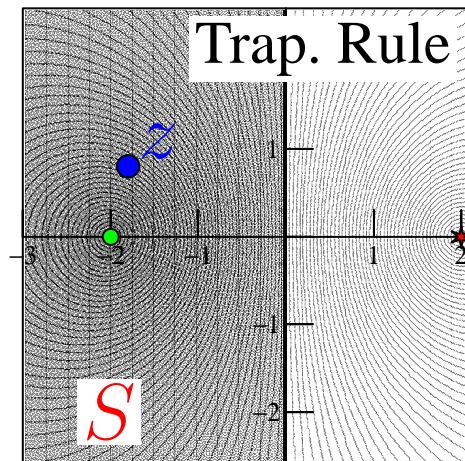
Expl. Euler

$$R(z) = 1 + z$$



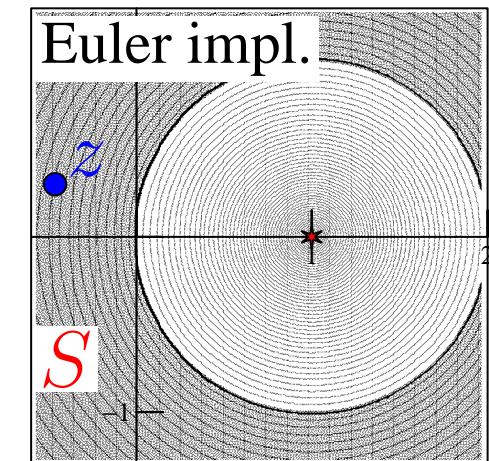
Trap. Rule

$$R(z) = \frac{1 + \frac{z}{2}}{1 - \frac{z}{2}}$$

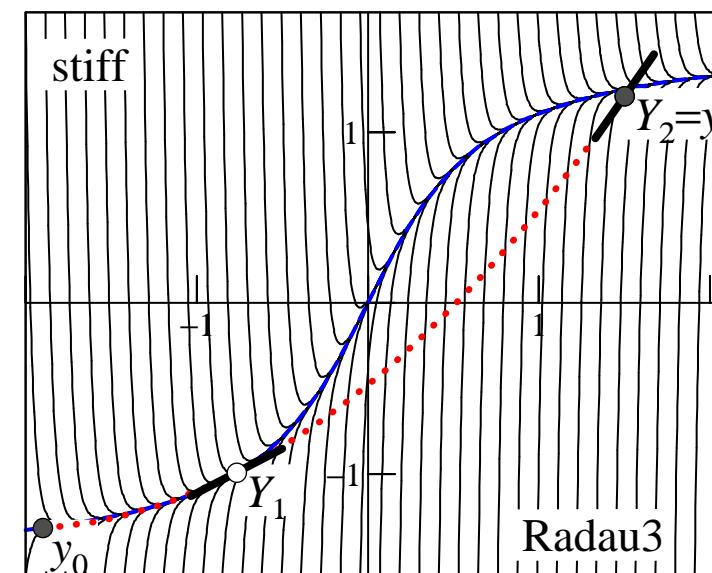
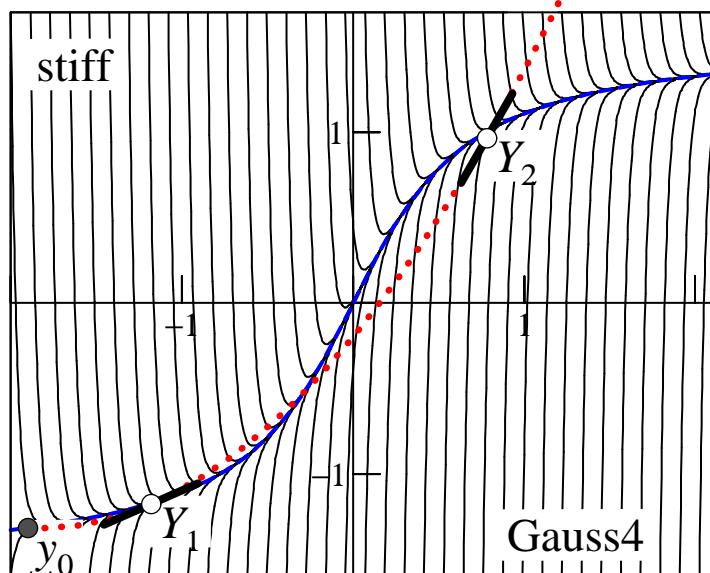
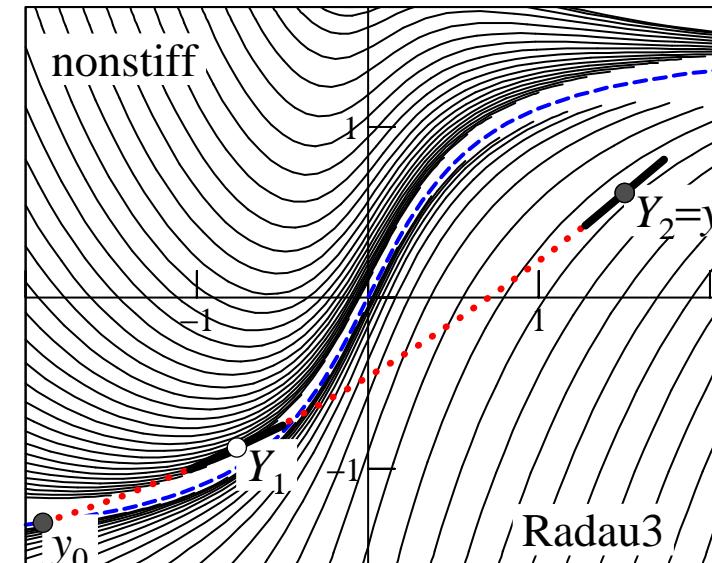
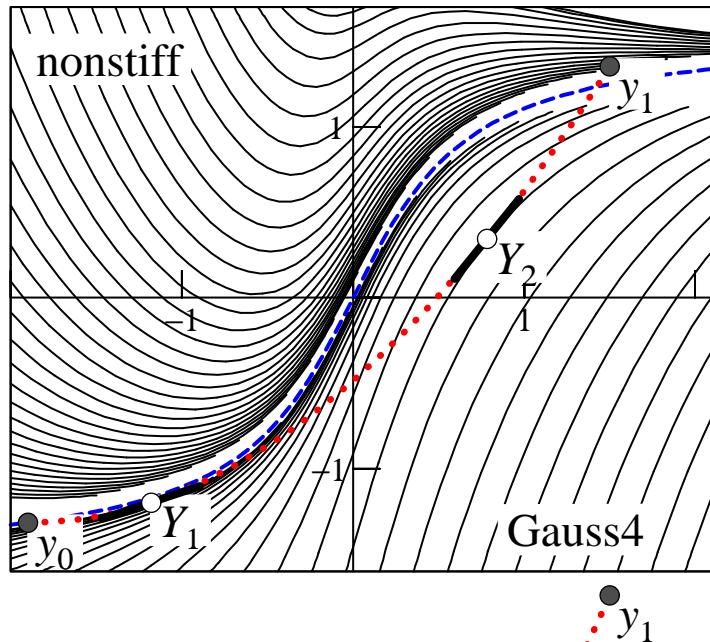


Impl. Euler

$$R(z) = \frac{1}{1 - z}$$



More general methods (Kuntzmann, Butcher 1964, Ehle 1968)



Theories

STABILITÄTSTHEORIEN FÜR STEIFE DIFFERENTIALGLEICHUNGEN

INHALT:

A-stable

A(∞)-stable

A(0)-stable

A₀-stable

A- $\tilde{\alpha}$ -stable

AN-stable

A_D-stable

algebraically stable

B-stable, B-consistent, B-convergent

BN-stable

BS-stable

BSI-stable

circle contractive

D-stable

D-stable

G-stable (A-contr.)

I-stable

internally stable

L-stable

internally L-stable

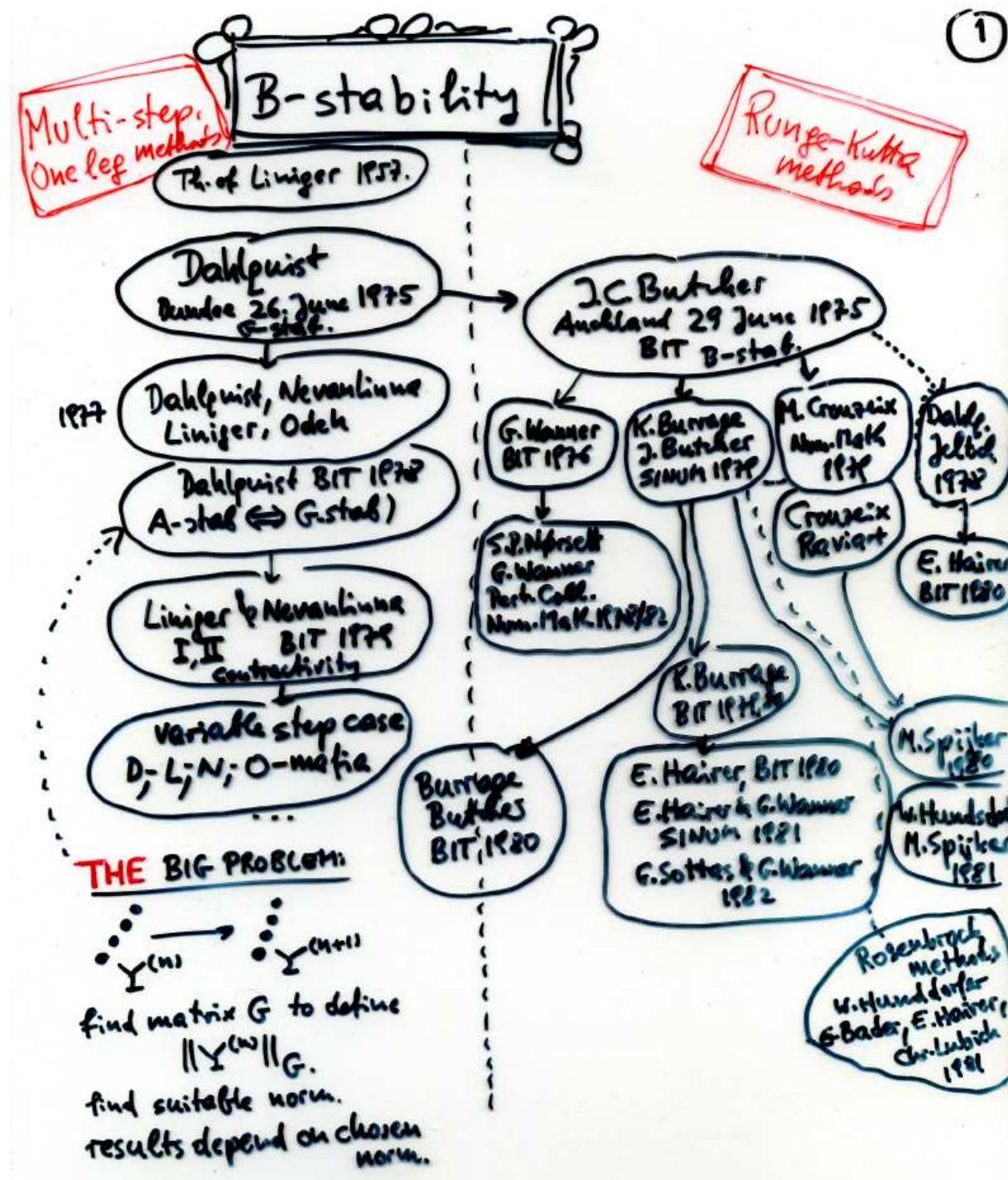
multipliers

O-stable

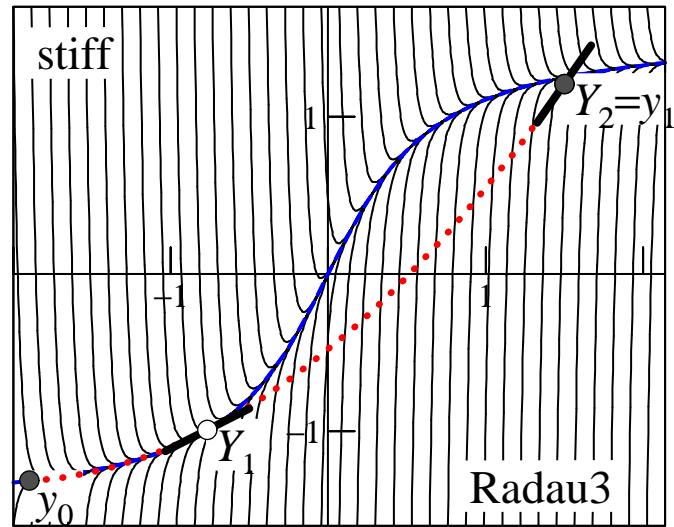
P-stable,

Stable R-stable S-stable stiffly stable variable stepsize splitting methods W-methoden ...

B-Stability



RADAU (General purpose code for stiff problems, E. Hairer):



$$\frac{4 - \sqrt{6}}{10}$$

$$\frac{88 - 7\sqrt{6}}{360}$$

$$\frac{296 - 169\sqrt{6}}{1800}$$

$$\frac{-2 + 3\sqrt{6}}{225}$$

$$\begin{array}{c|cc} 1 & \frac{5}{12} & -\frac{1}{12} \\ 3 & \frac{1}{12} & \frac{1}{12} \\ \hline 1 & \frac{3}{4} & \frac{1}{4} \\ \hline & \frac{3}{4} & \frac{1}{4} \end{array}$$

$$\frac{4 + \sqrt{6}}{10}$$

$$\frac{296 + 169\sqrt{6}}{1800}$$

$$\frac{88 + 7\sqrt{6}}{360}$$

$$\frac{-2 - 3\sqrt{6}}{225}$$

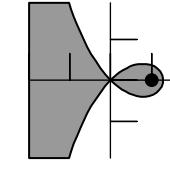
$$\frac{16 - \sqrt{6}}{36}$$

$$\frac{16 + \sqrt{6}}{36}$$

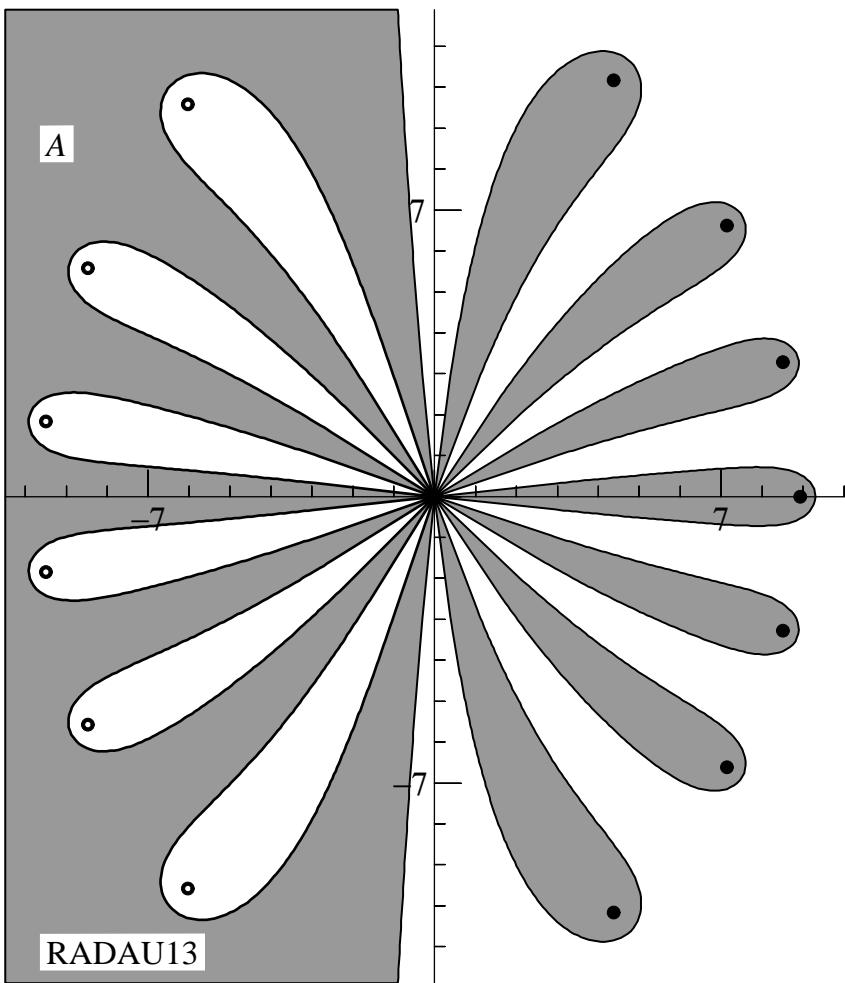
Radau3

Radau5

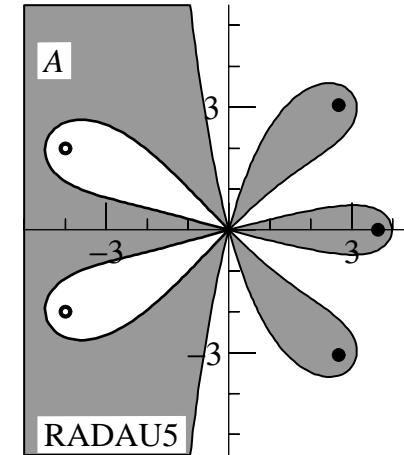
Their order stars:



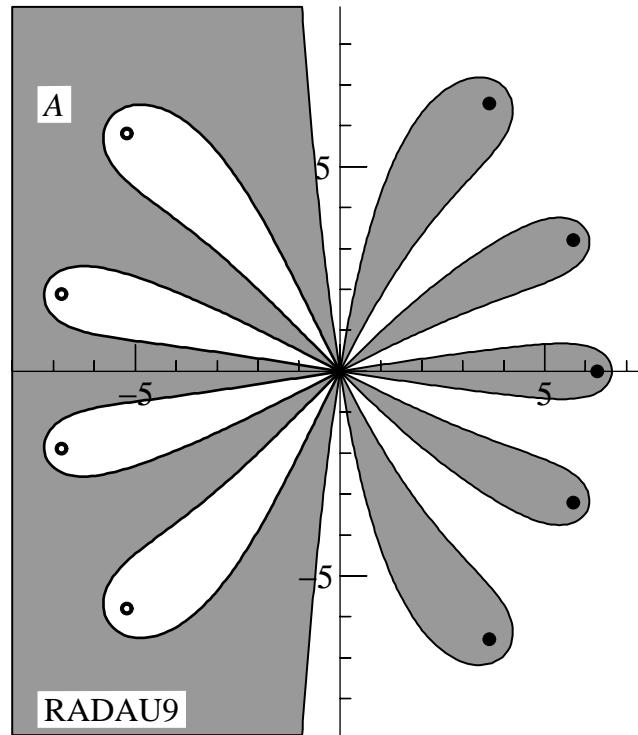
RADAU1



RADAU13

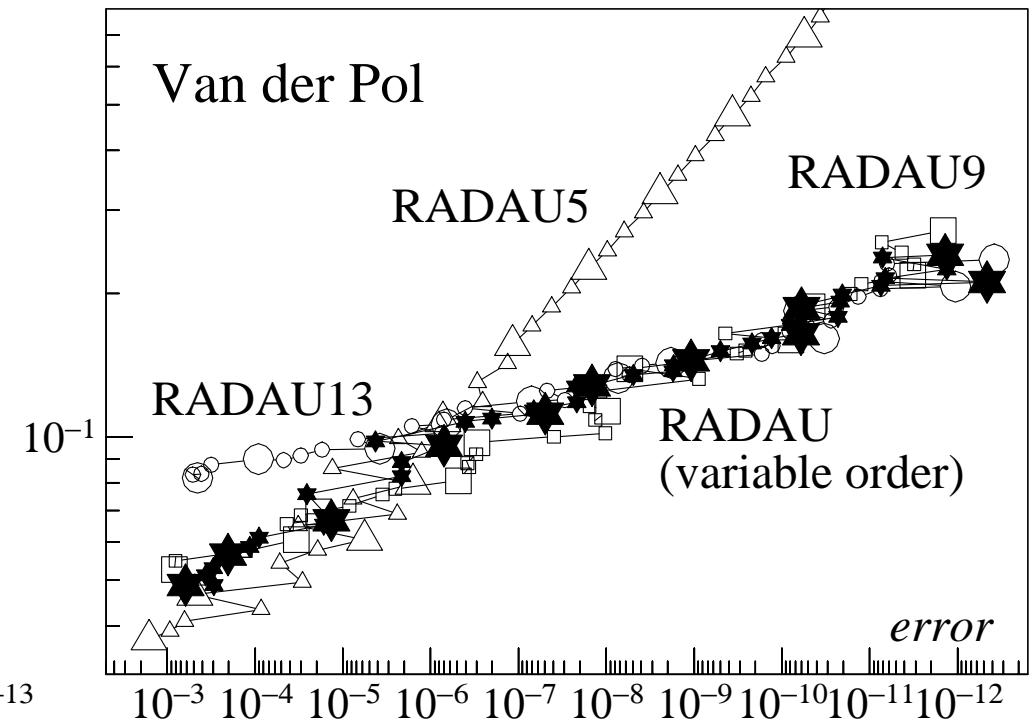
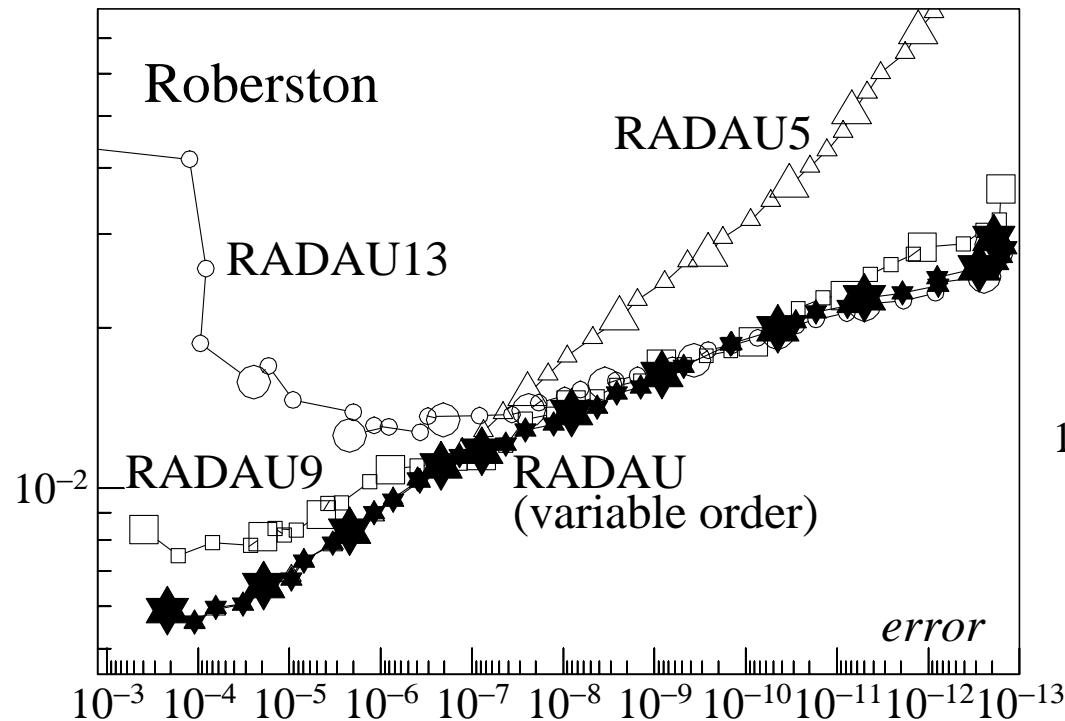


RADAU5

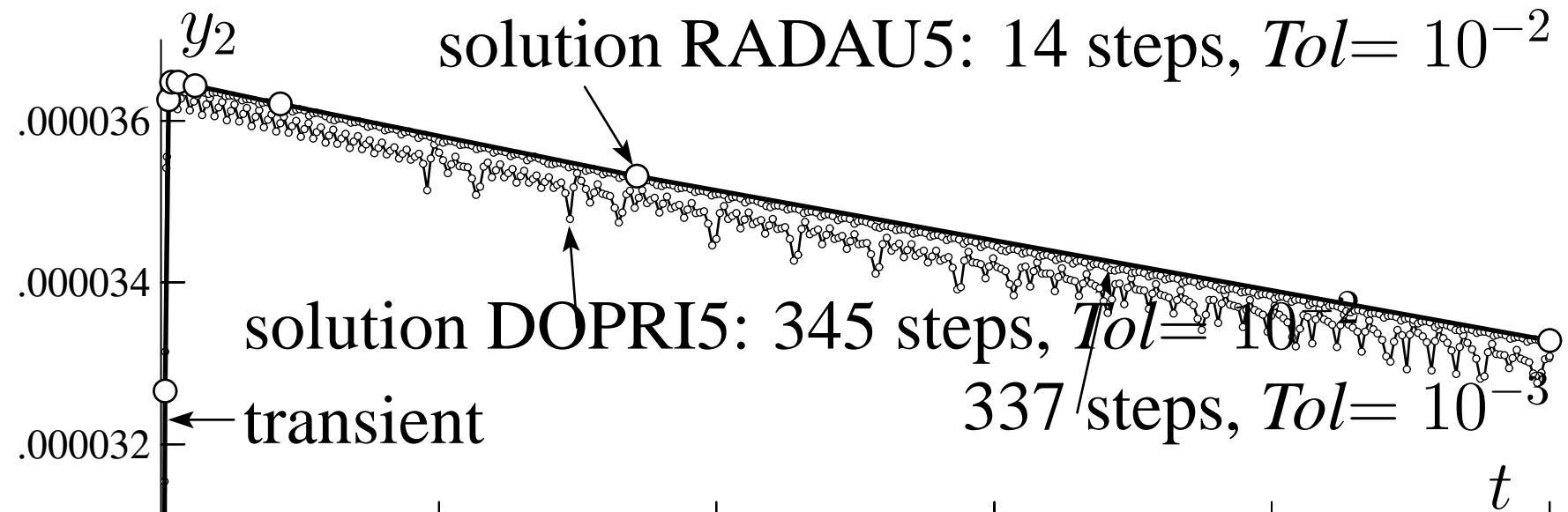


RADAU9

Variable order RADAU code:



Robertson reaction:



The Price to Pay: Fully Implicit Method..

The Price to Pay: Fully Implicit Method..

Explicit Methods ..?

The Controversy between Multistep and Runge-Kutta

But surely the predictor-corrector techniques (Milne's for example) will result in one getting an answer to the same accuracy in a shorter time simply because information outside a single interval is used...

(Dr. J.M. Bennett, Sydney, in a discussion 1956)

The greater accuracy and the error-estimating ability of predictor-corrector methods make them desirable for systems of any complexity. . . . Runge-Kutta methods still find applications in starting the computation . . .

(A. Ralston, *Math. Comput.* 1962)

Circle Theorems (Jeltsch, Nevanlinna)

19.10.78

I) Kreis-Sätze

$$D_r = \{ \mu \mid |\mu + r| \leq r \}$$

Möchte $D_r \subset S$, r so gross wie möglich.

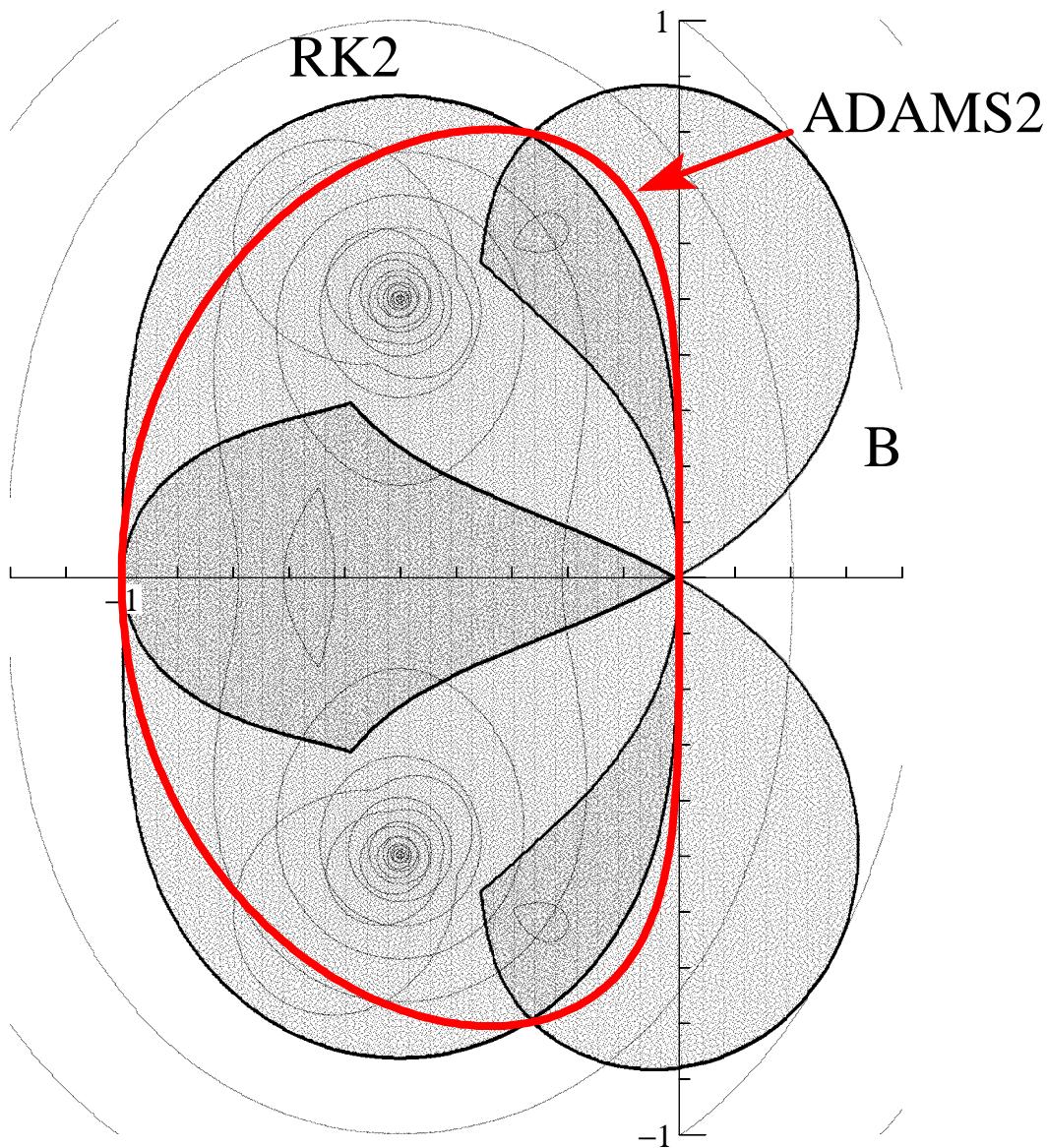
(Warum $D_r \subset S$, Stabilitäts Resultat kann für nichtlineare Fall auch gezeigt werden)

Satz 3 m -stufig, $P(\mu)$ irreduzibel

$$\Rightarrow D_m \not\subset S \text{ oder } P(\mu) = \left(1 + \frac{\mu}{m}\right)^m$$

Bem. 1-4 Siehe 1.13.1 - 1.13.4

Jeltsch-Nevanlinna Theorem.



$$|\zeta_{\text{adams}}(\mu)| > |R_{\text{rk}}(\mu)|$$

$$\Rightarrow S_1^{\text{scal}} \not\supseteq S_2^{\text{scal}}$$

$$\text{and } S_1^{\text{scal}} \not\subset S_2^{\text{scal}}$$

there is no overall
good explicit method !

Is there really no hope ...?

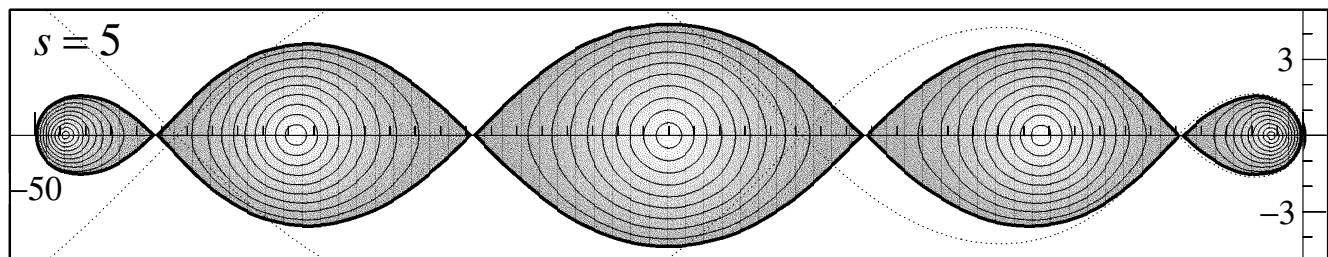
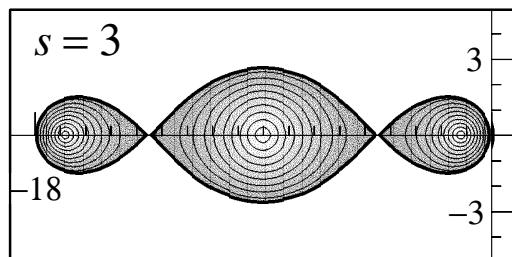
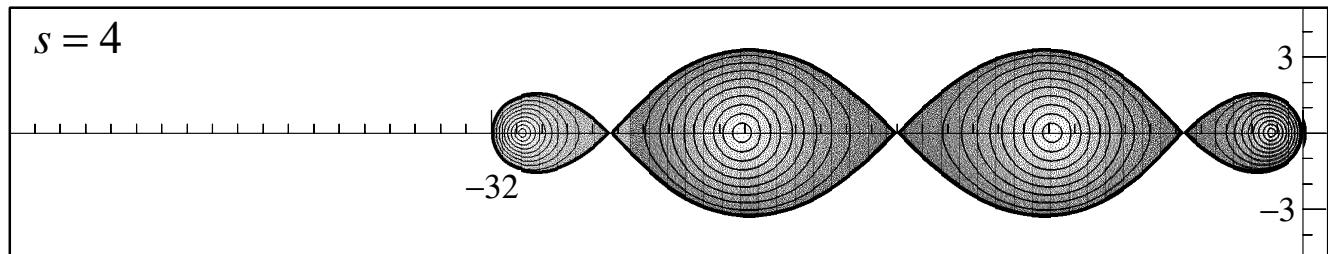
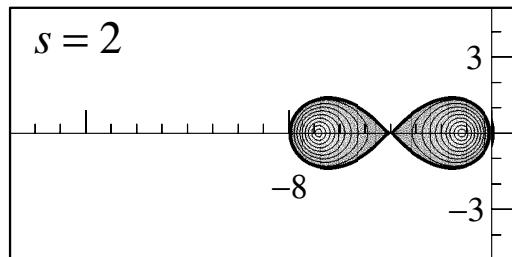
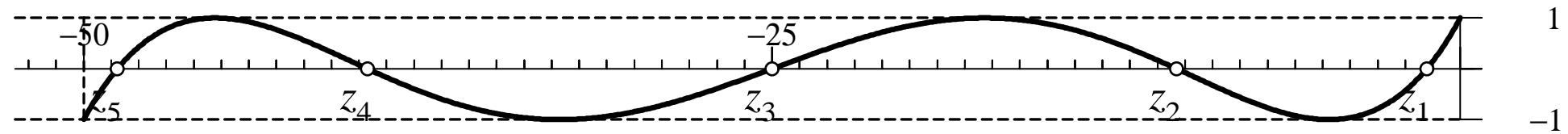
Yes, if, e.g., we know that eigenvalues are real.

Problem. Find $R(z) = 1 + z + a_2z^2 + \dots + a_sz^s$ as stable as long as possible for $z \rightarrow -\infty$.

Yes, if, e.g., we know that eigenvalues are real.

Problem. Find $R(z) = 1 + z + a_2 z^2 + \dots + a_s z^s$ as stable as long as possible for $z \rightarrow -\infty$.

Answer. $R(z) = T_s(1 + z/s^2)$ (**Chebyshev polynomial**)



Yes, if, e.g., we know that eigenvalues are real.

Problem. Find $R(z) = 1 + z + a_2 z^2 + \dots + a_s z^s$ as stable as long as possible for $z \rightarrow -\infty$.

Answer. $R(z) = T_s(1 + z/s^2)$ (**Chebyshev polynomial**)

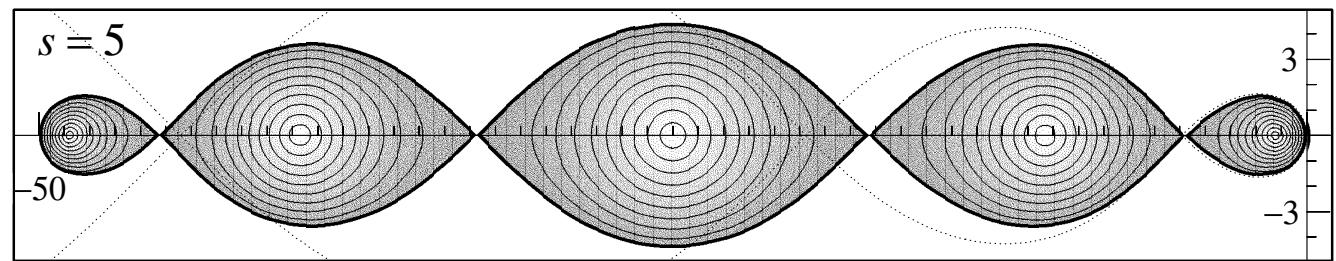
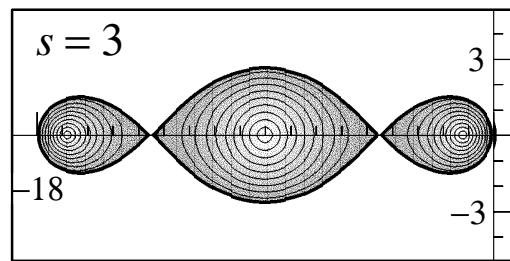
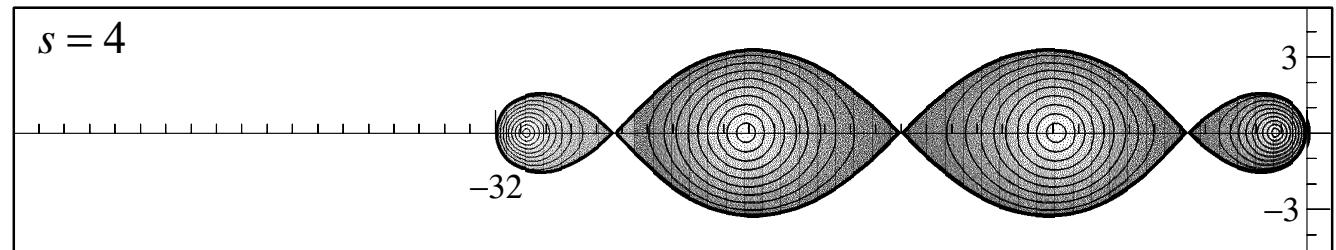
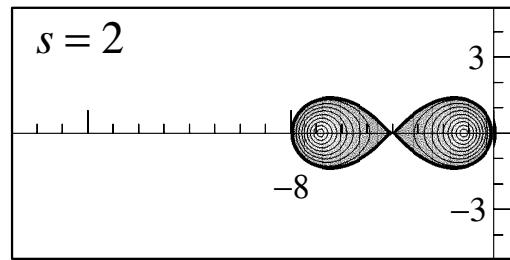
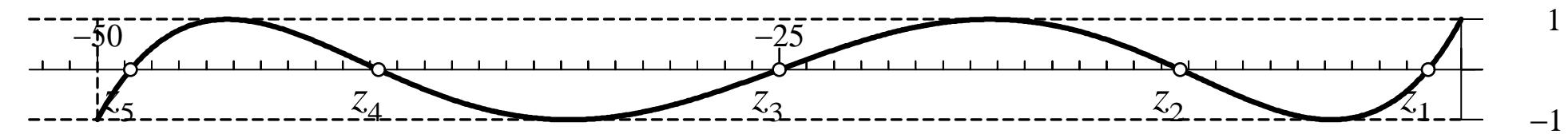
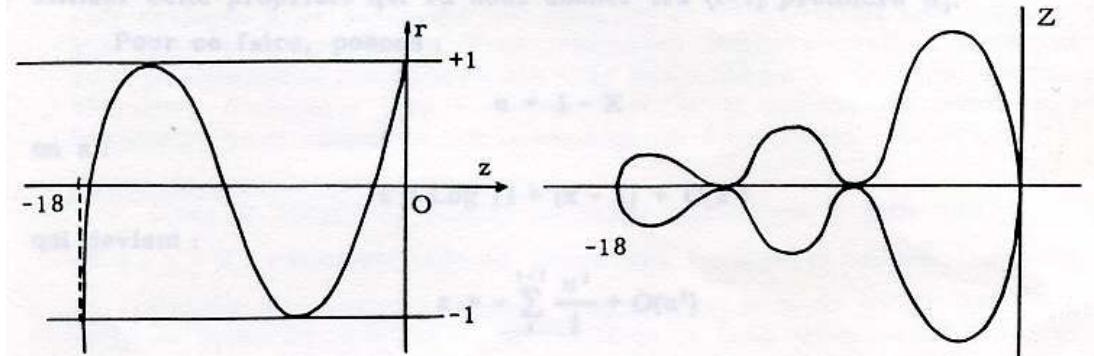


Illustration from
Guillou-Lago (1961):

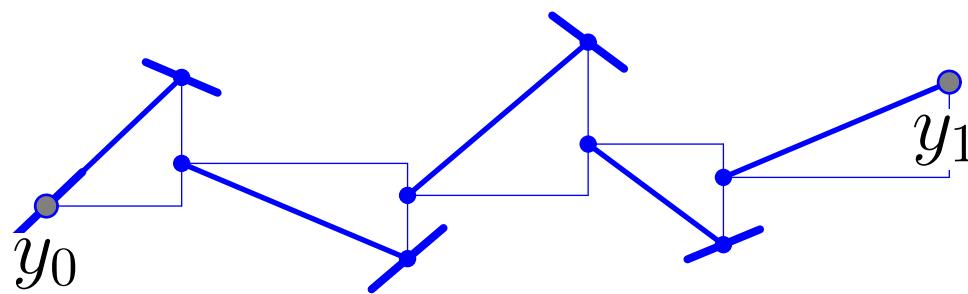


Realization for nonlinear problems:

Guillou-Lago, Saul'ev, Lebedev:

$$R_s(z) = \prod_{i=1}^s (1 + \delta_i z) \quad \Rightarrow \quad \text{composition of Euler steps.}$$

Van der Houwen-Sommeijer: Three term recursion for T_n \Rightarrow

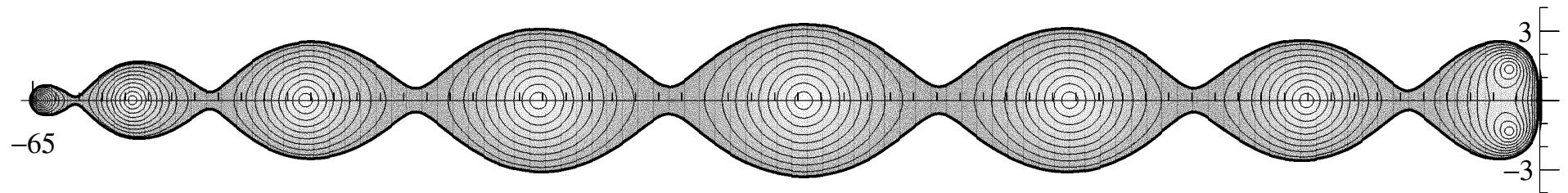
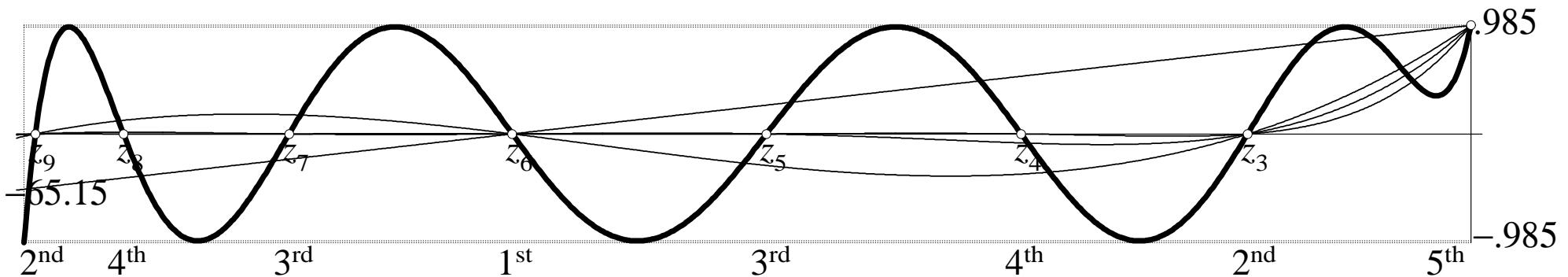


composition of 2-step formulas.

Methods of Order 2:

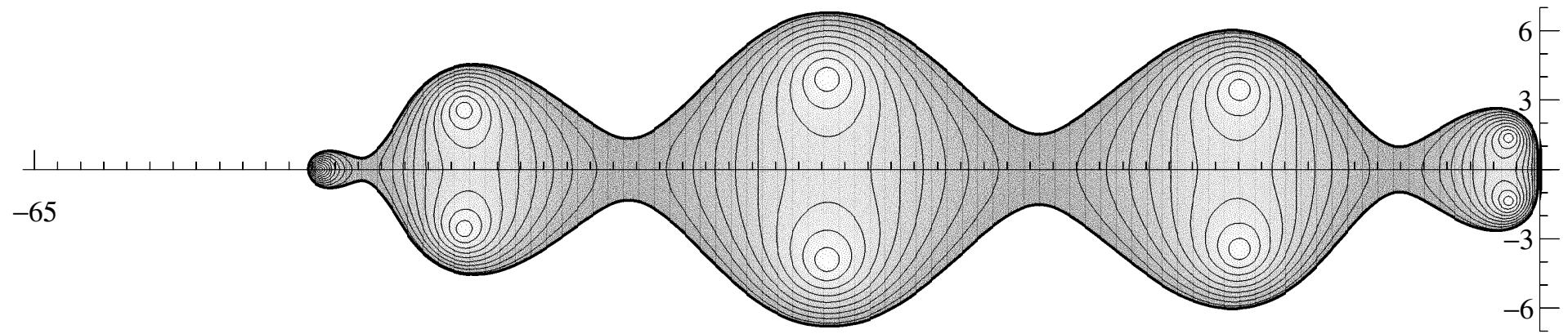
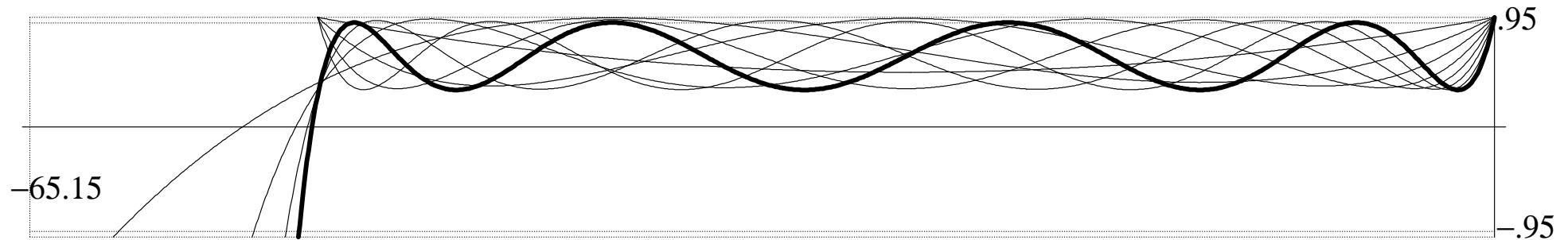
$$R_s(z) = 1 + z + \frac{z^2}{2} + a_3 z^3 + \dots + a_s z^s$$

Lebedev: Zolotarev polynomials:



Van der Houwen-Sommeijer-Verwer:

Shift and scaling of T_n to produce 2nd order:



⇒ some loss of stability, but three term recursion preserved.

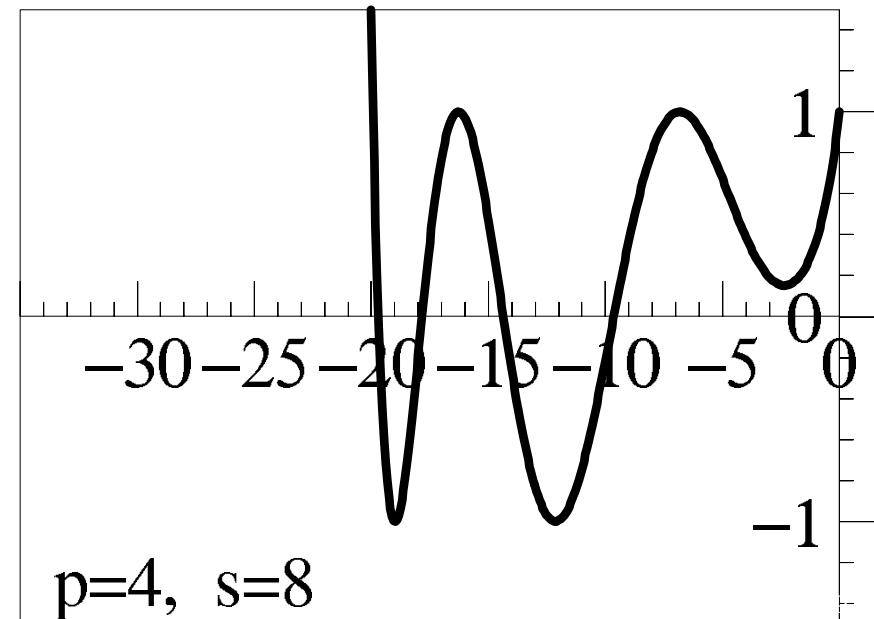
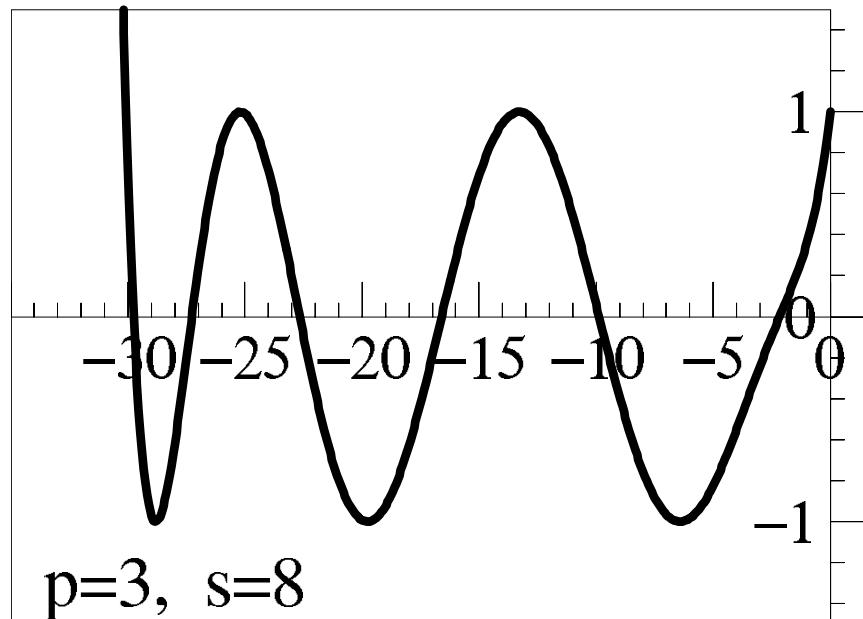
Higher Orders.

$$R_s^p(z) = 1 + z + \dots + \frac{z^p}{p!} + a_{p+1}z^{p+1} + \dots + a_sz^s$$

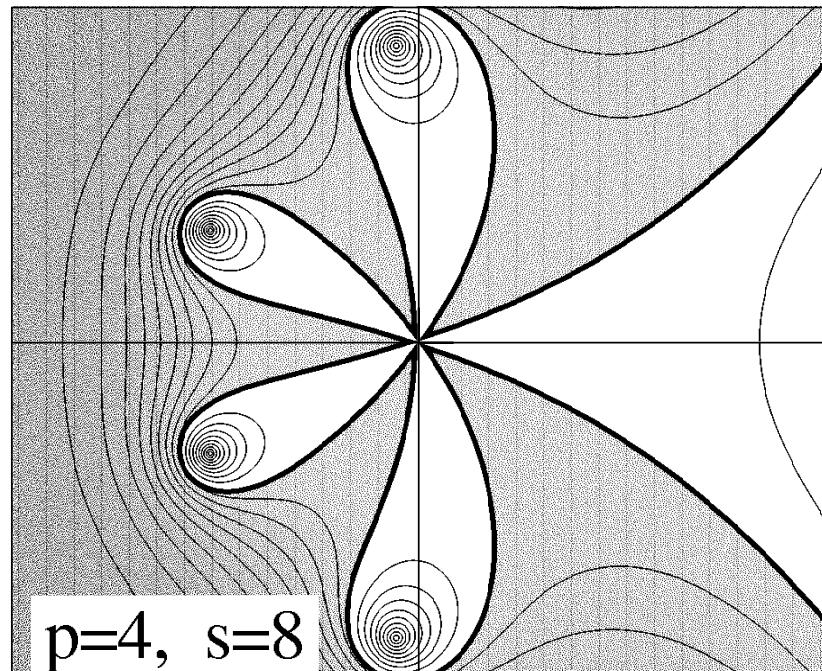
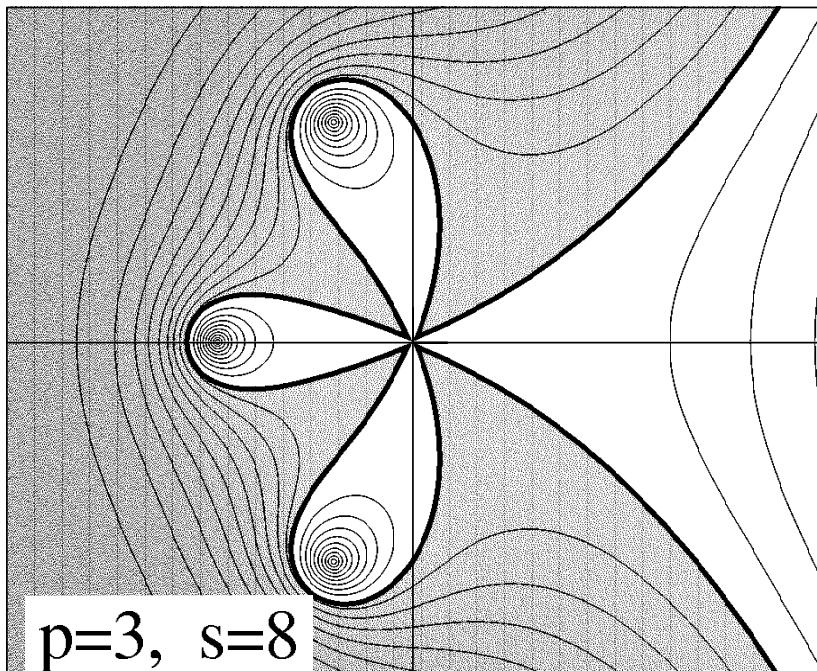
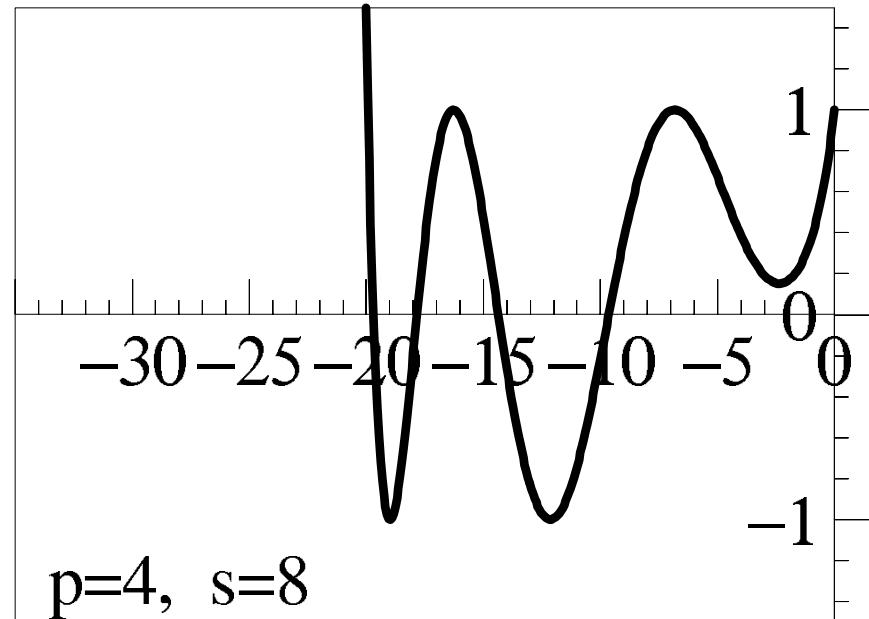
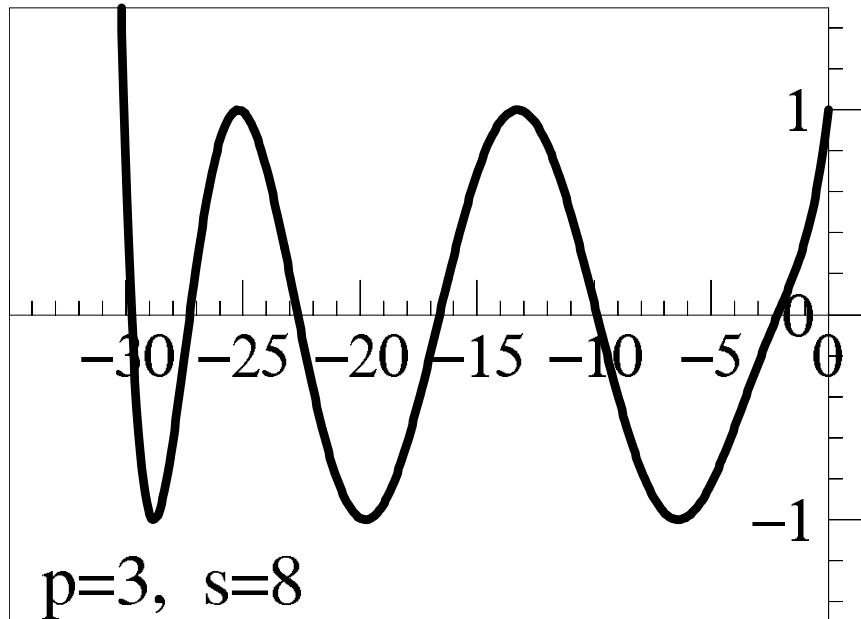
Problem (Lebedev 1995) Theorem (Abdulle 2000)

$R_s^p(z)$ possesses exactly p complex zeros if p is even and exactly $p - 1$ complex zeros if p is odd. Remaining real zeros distinct $\in (-l_s^p, 0)$.

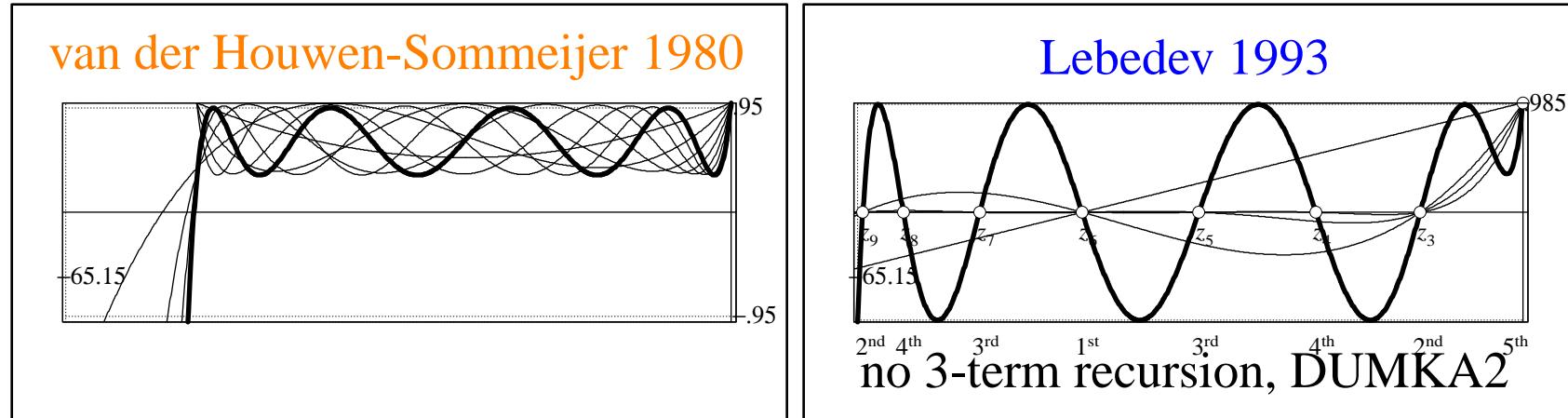
Error constants: for p given $C_{p+1}^p > C_{p+2}^p > \dots > 0$.



Proof by Order-Stars.



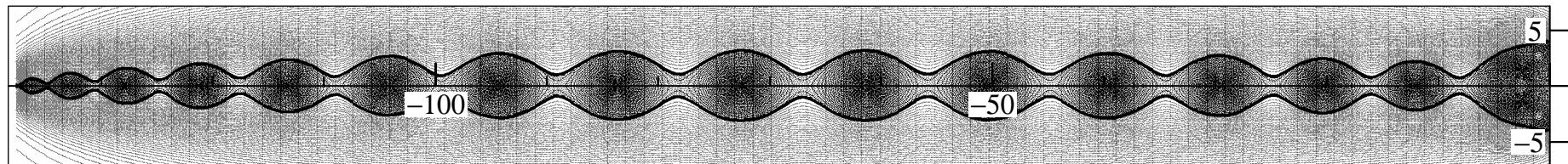
Towards ROCK: (Abdulle-Medovikov 1999, Abdulle 2002):



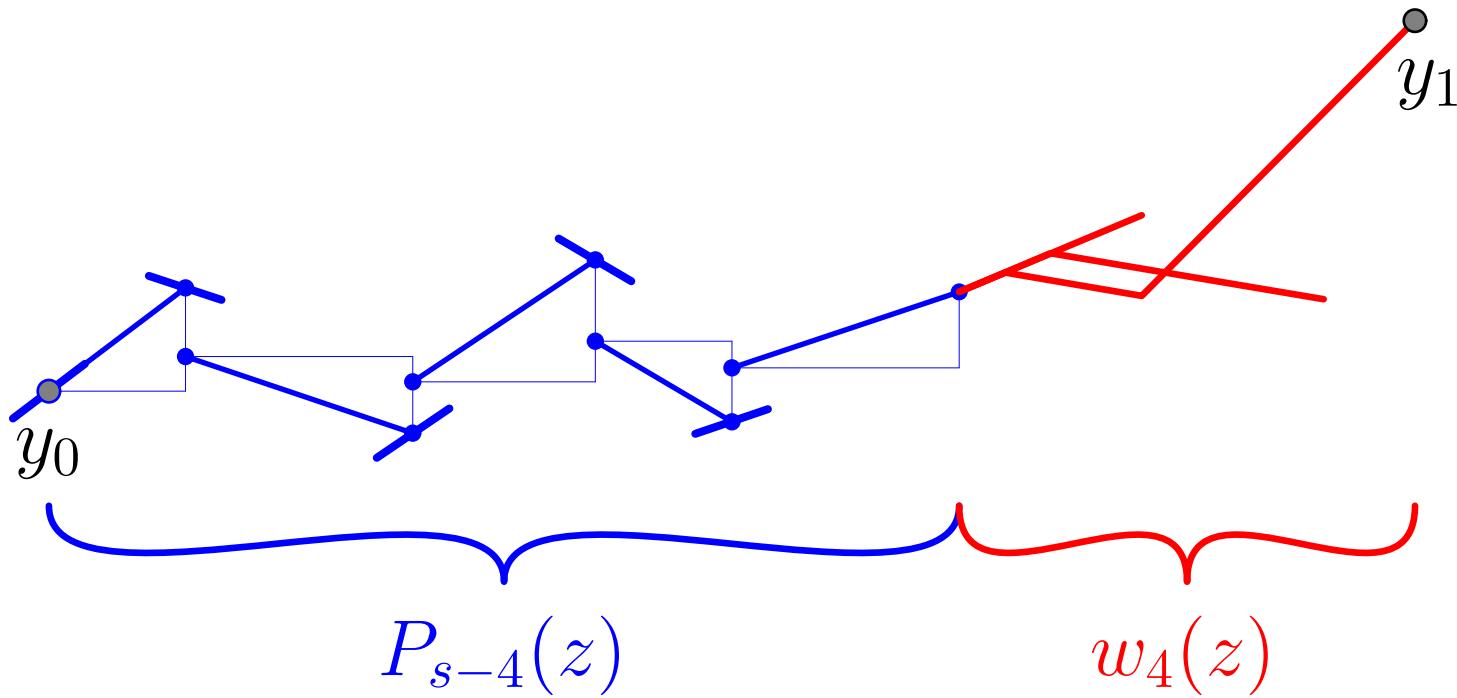
find approx. of order 4 to e^z

$$R_s(z) = w_4(z) P_{s-4}(z), \quad P_j(x) \text{ orthog. w.r. } \frac{w_4^2(x)}{\sqrt{1-x^2}}$$

Thm. Bernstein (1930): $\Rightarrow R_s(z)$ ‘nearly’ optimal;
orthogonality: \Rightarrow 3-term recursion .



Realization for nonlinear problems:



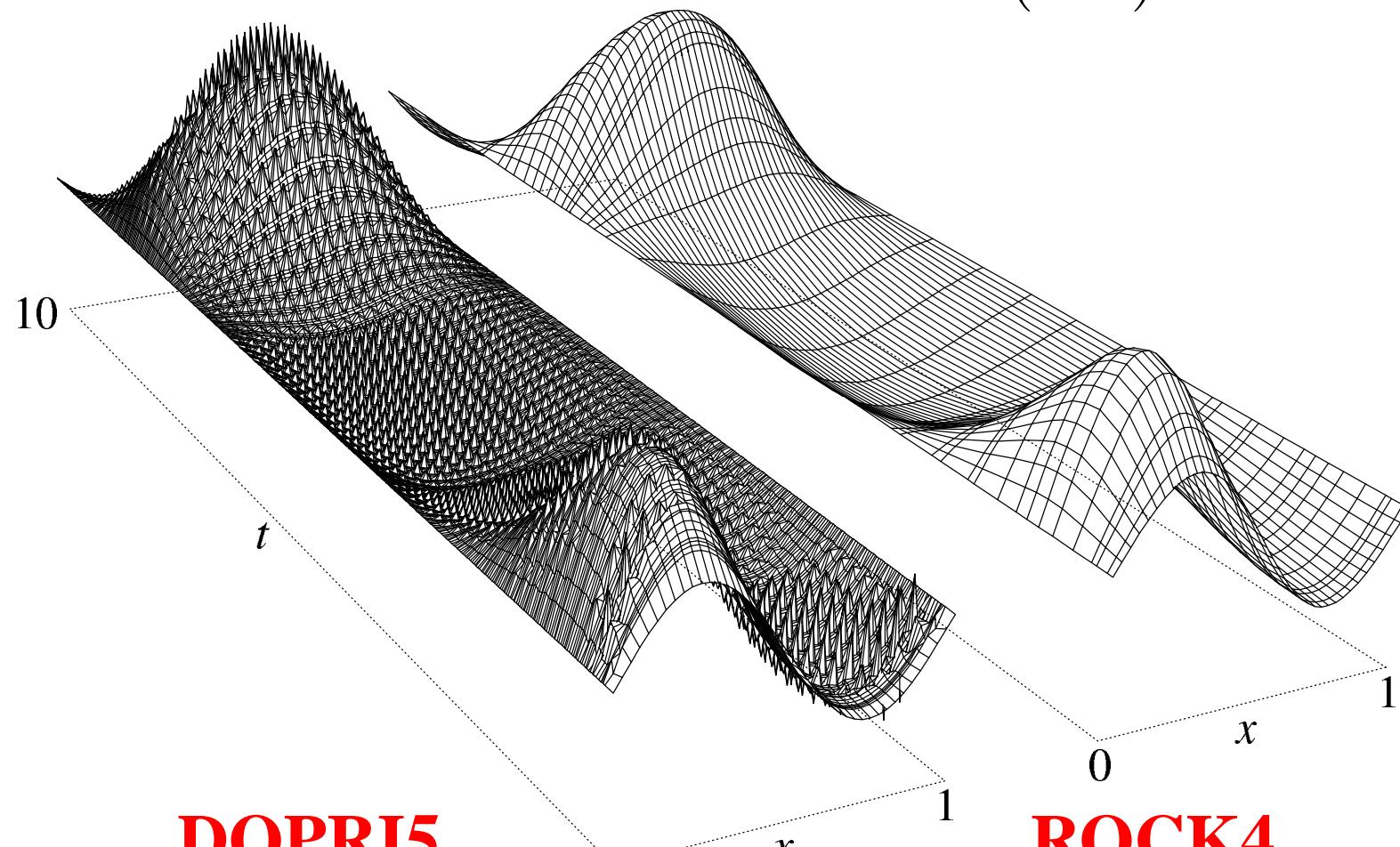
blue method given (from 3-term recursion), compose with red classical 4-stage RK method and achieve order 4 with the help of the **Butcher Group**

⇒ code **ROCK4**.

Example. Reaction-Diffusion (Brusselator with 1D diffusion).

$$\frac{\partial c}{\partial t} + f(c) = D \Delta c,$$

CFL: $\frac{\Delta t}{(\Delta x)^2} \leq \frac{1}{2D}$



DOPRI5

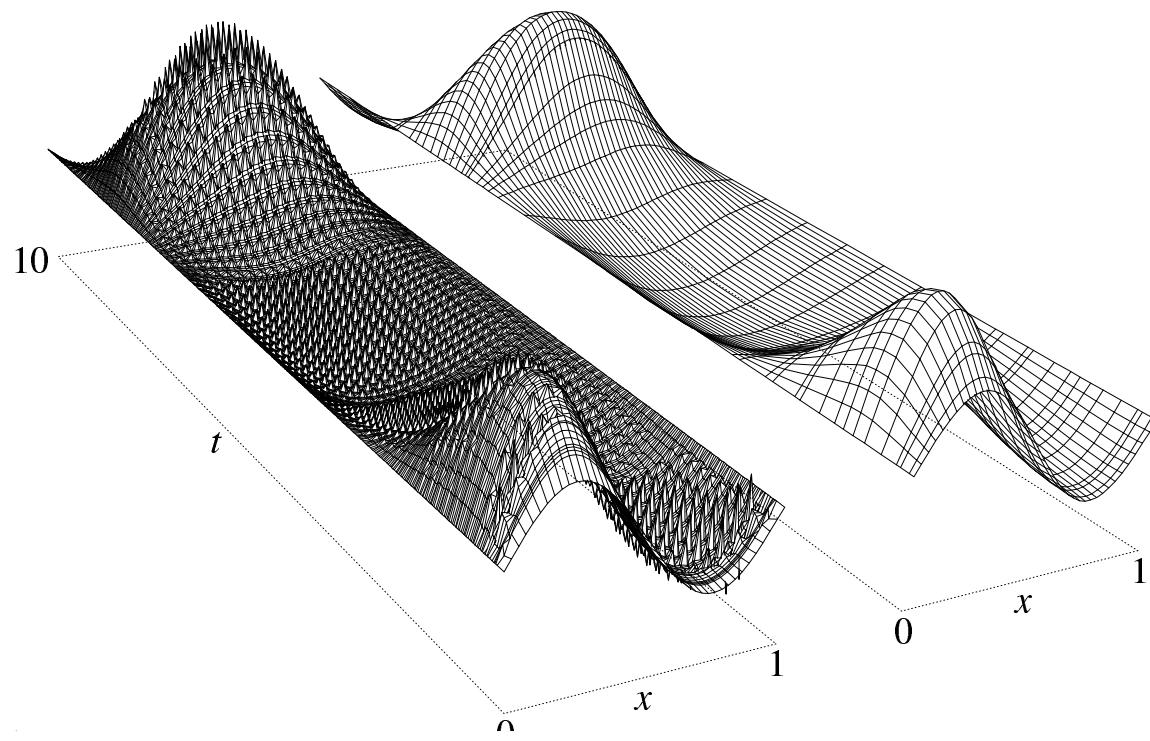
406 steps

Fcn. evaluation $C/(\Delta x)^2$

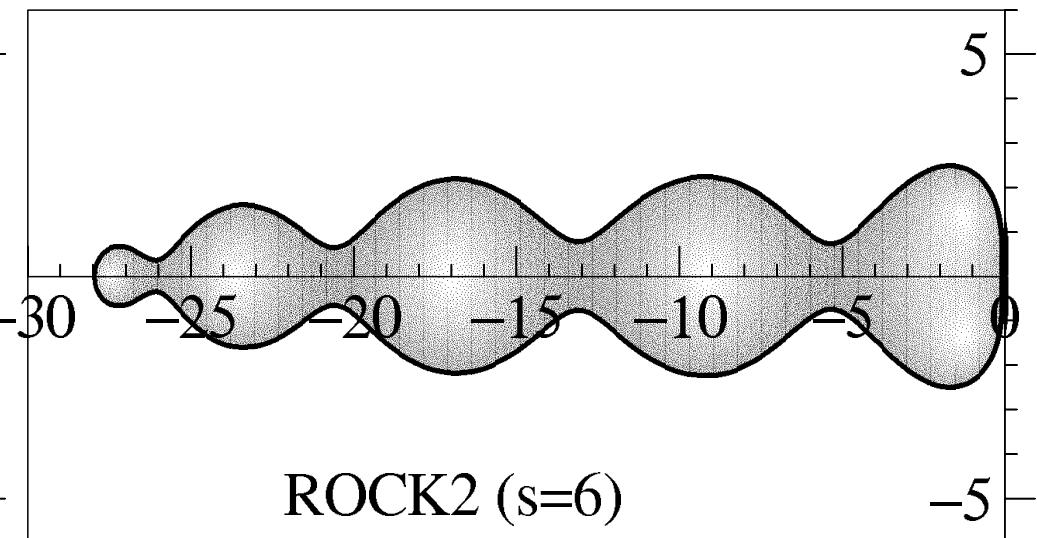
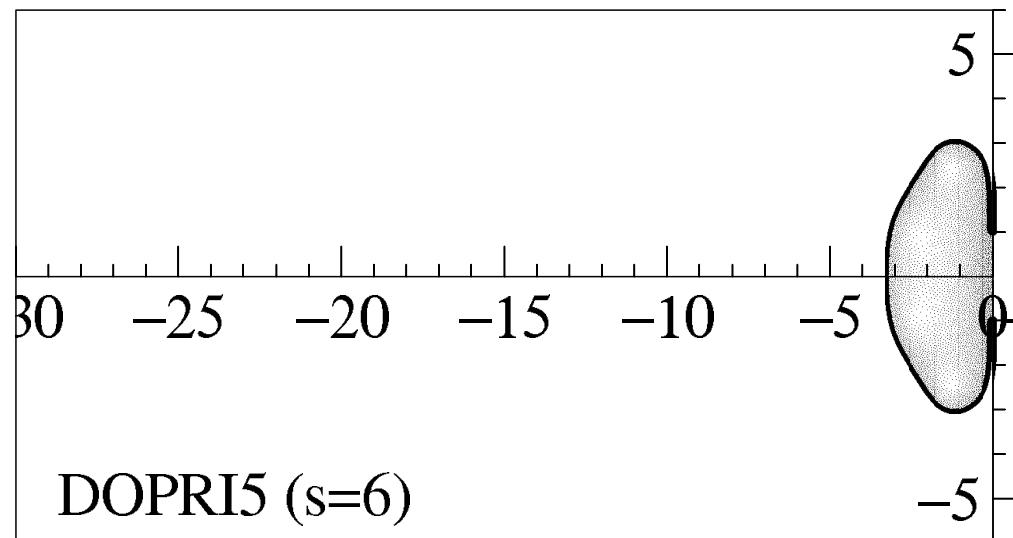
ROCK4

23 steps

Fcn. evaluation $\bar{C}/(\Delta x)$



Comparison of Stability Domains



Other Applications. (advection-diffusion-reaction)

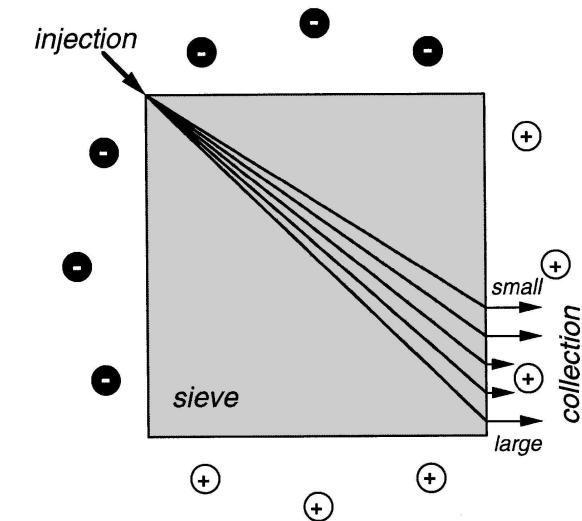
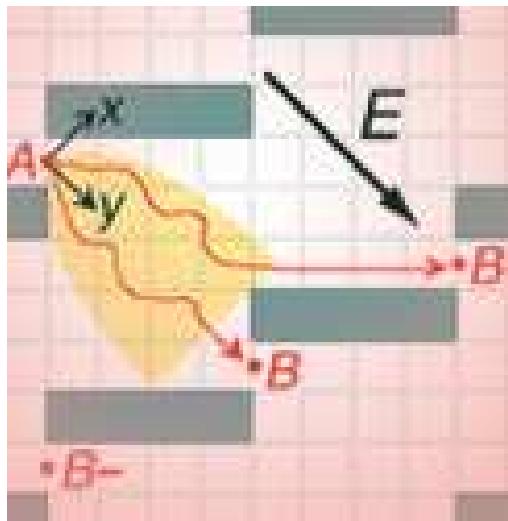
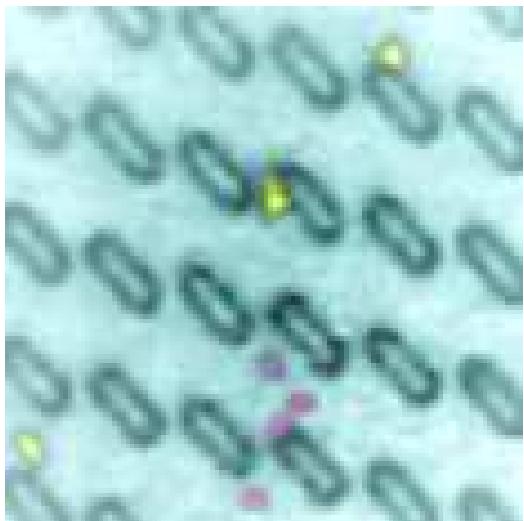
Nanoscale Tunneling Devices, Stiff biogeochemical models,
Aggregation processes of molecules, Quantum problem,
Competition between Protein Folding and Aggregation, Soft
Tissue Simulation, Simulation of the Saint-Venant System,
Modelisation of High Current Arc, etc.

Other Applications. (advection-diffusion-reaction)

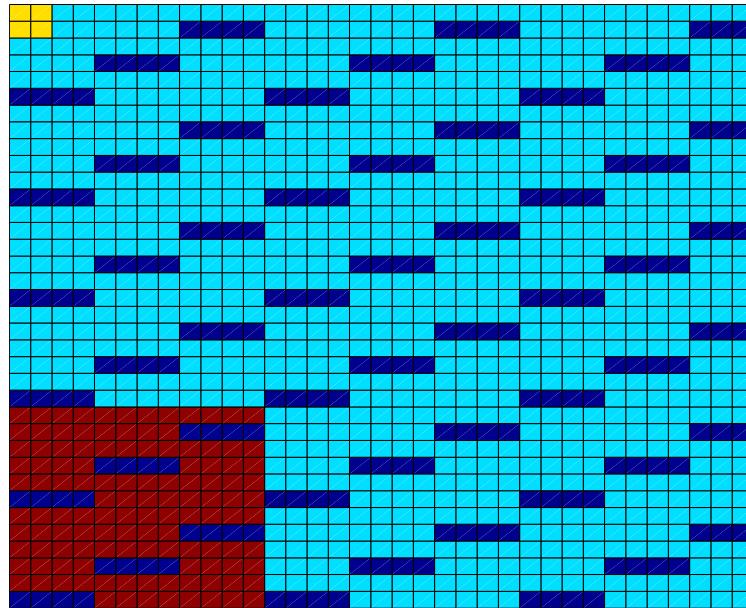
Nanoscale Tunneling Devices, Stiff biogeochemical models, Aggregation processes of molecules, Quantum problem, Competition between Protein Folding and Aggregation, Soft Tissue Simulation, Simulation of the Saint-Venant System, Modelisation of High Current Arc, etc.

More detailed Application. (Transport in microarray)

DNA separation in heterogeneous media (Duke and Austin, Ertas 1998-2003)



Multiscale transport modeling (Abdulle-Attinger).



Charged particles advected by electrical potential

$$v^\varepsilon = -\rho a^\varepsilon \nabla u, \quad a^\varepsilon = a(x/\varepsilon)$$

Elliptic Equ. $\nabla \cdot (a^\varepsilon \nabla u^\varepsilon) = 0, \quad u|_{\partial\Omega} = u_0$

Adv.-Diff. $\frac{\partial c^\varepsilon}{\partial t} + v^\varepsilon \cdot \nabla c^\varepsilon = D \Delta c^\varepsilon, \text{ with I. \& B. cond.}$

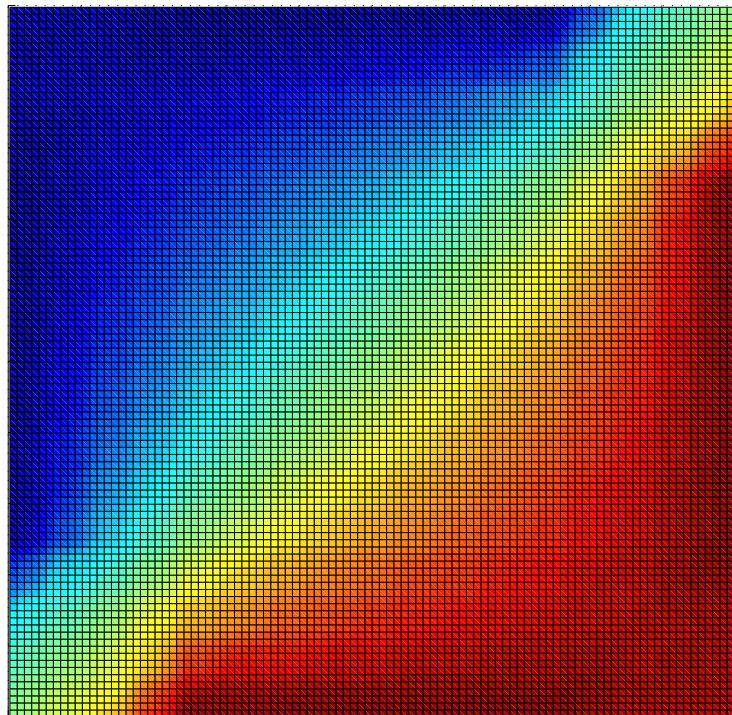
Multiscale:

Obstacles \sim micrometer \ll Device \sim centimeter

Computational Simulation:

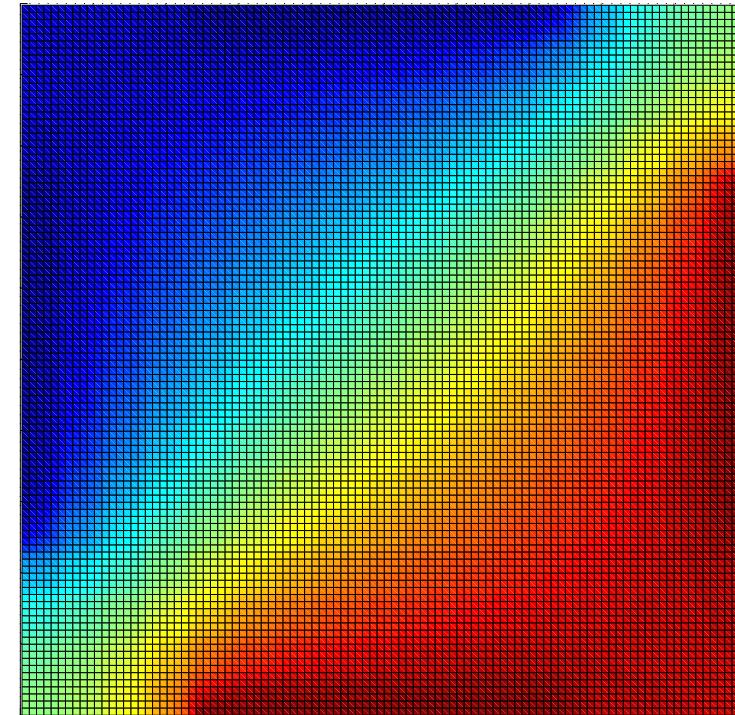
use finite element multiscale method (FE-HMM, Abdulle, E ...) for the multiscale elliptic problem ...

Reconstructed small scale solution $u^{e,h}$, $H=1/8$



FE-HMM DOF $\sim 10^3$

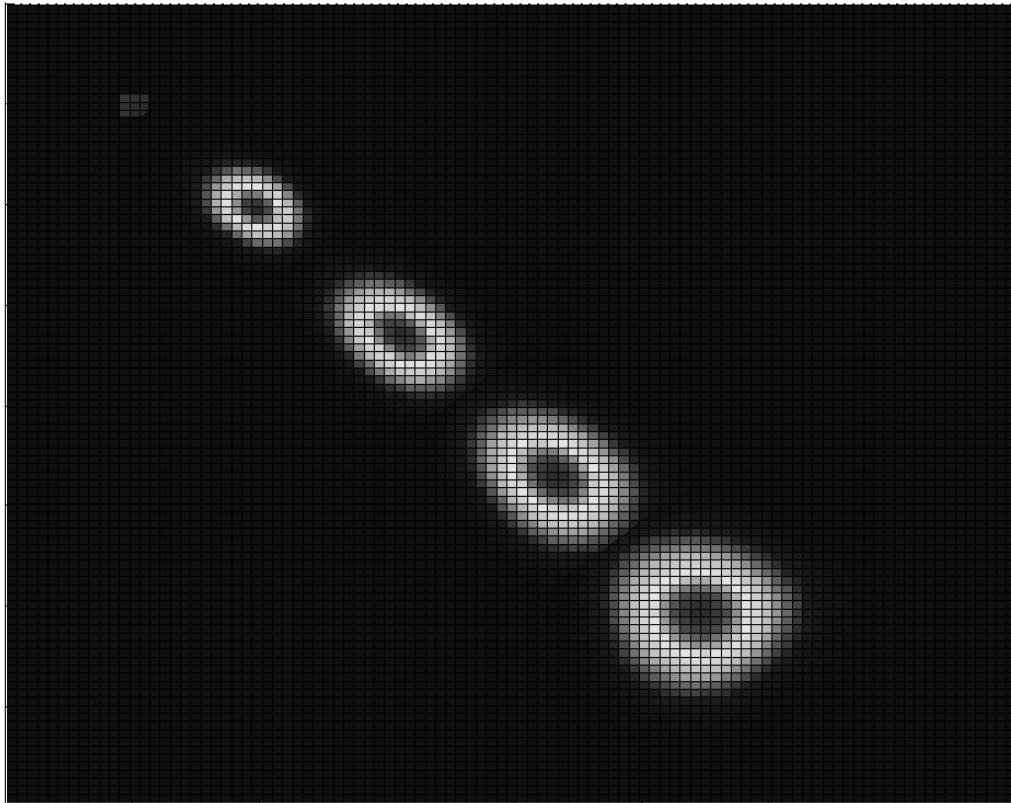
Small scale solution u^e



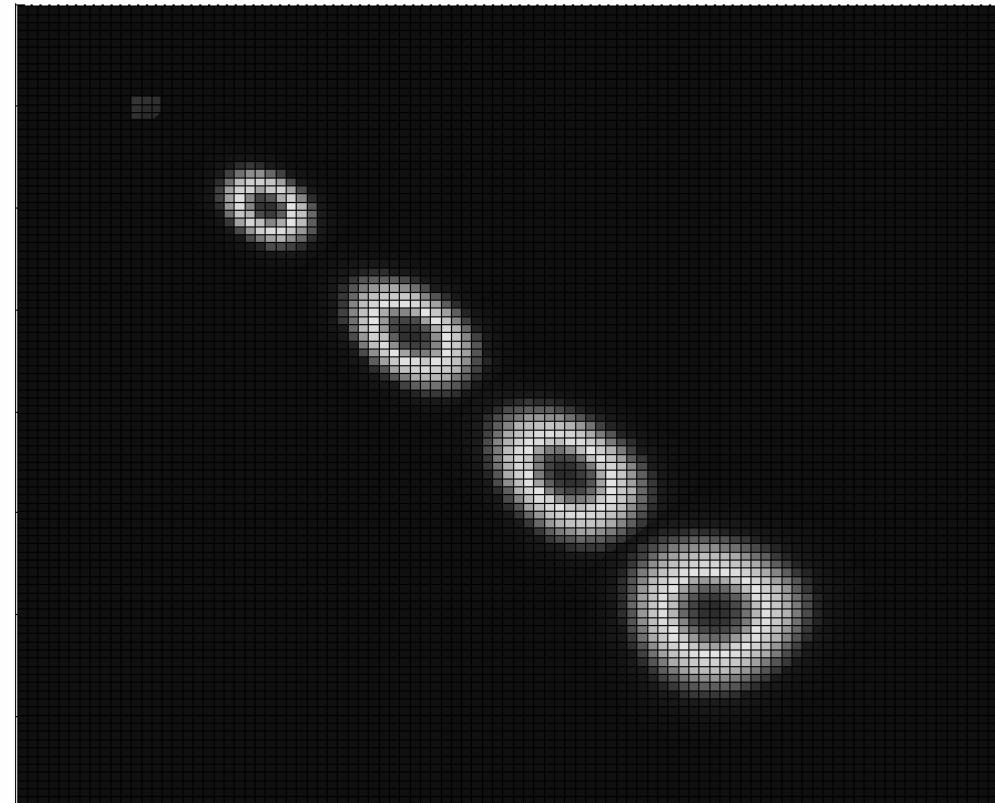
FEM DOF $\sim 10^6$

... and ROCK for the transport problem:

Particle trajectory in microdevice (appr. vel. $H=1/8$)



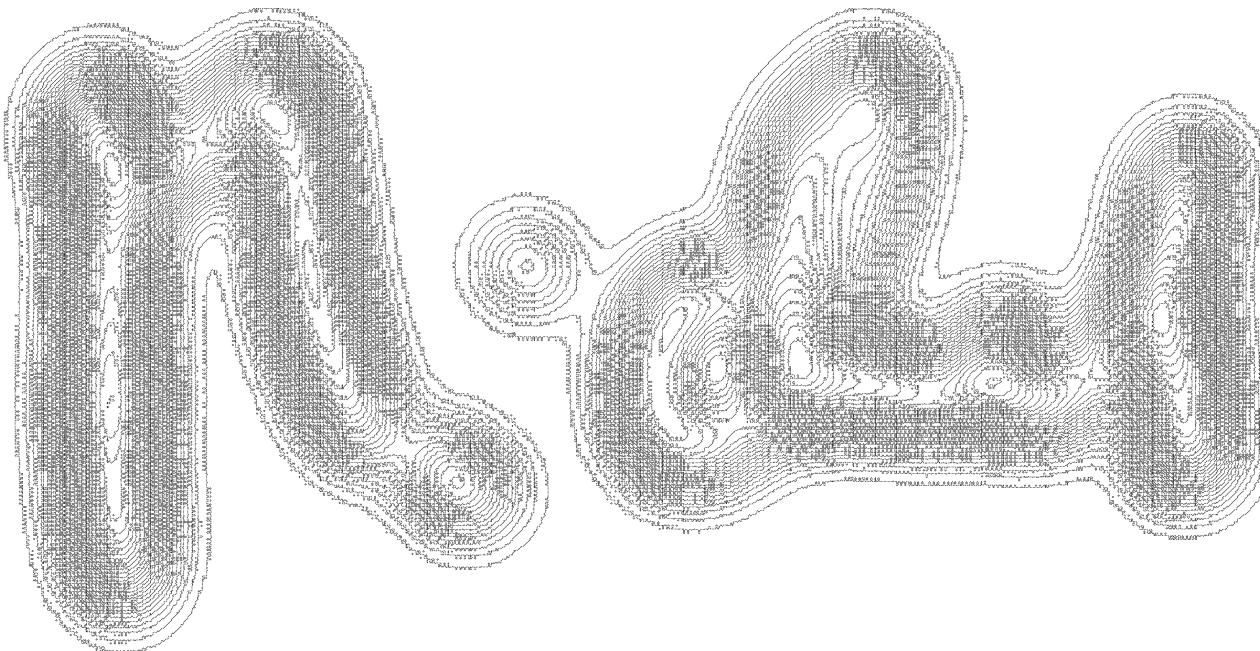
Particles trajectory in microdevice (ref. velocity)

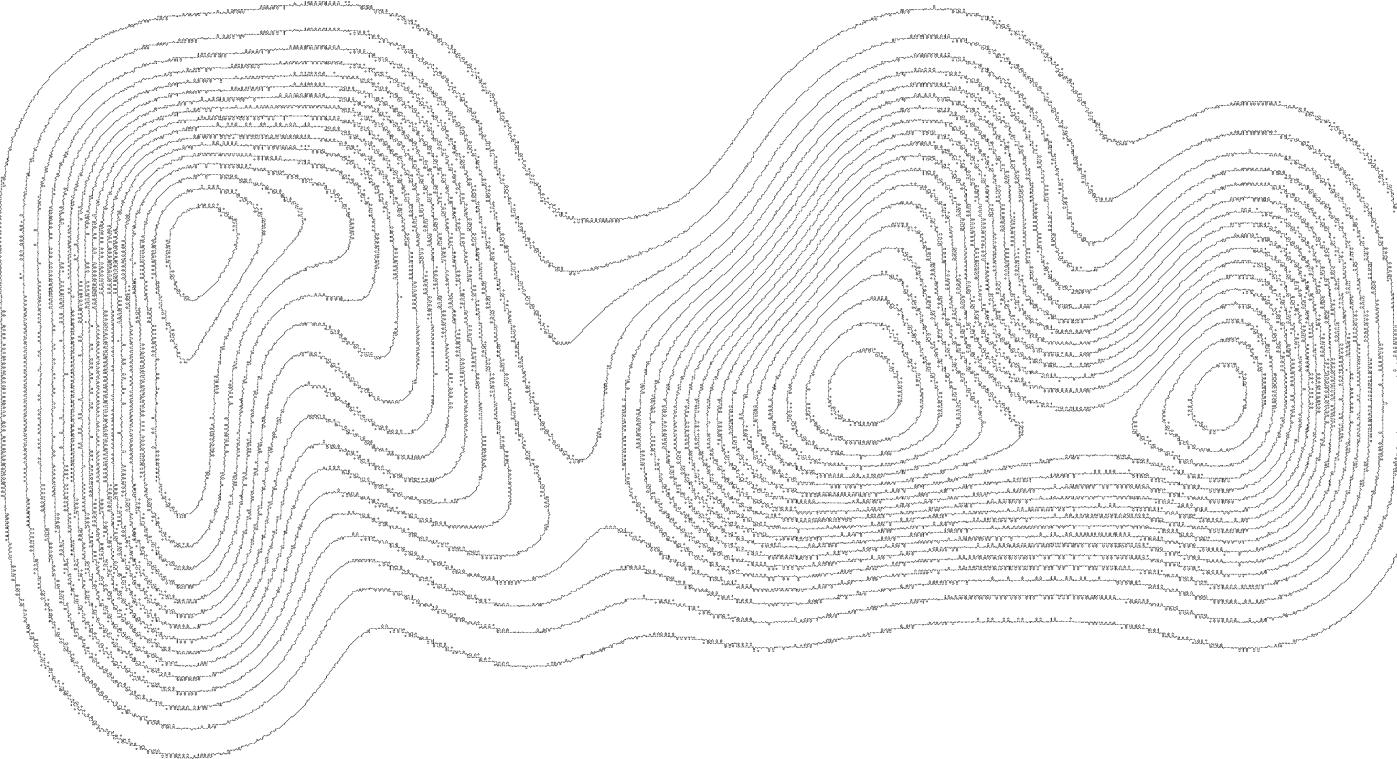


Cordiales félicitations et nos meilleurs voeux !!



What is ROCK doing with you?





Good Bye !! Au revoir !! Do svidaniia !!
Tot ziens !! Uff wiederluege !!
Auf Wiedersehen !!